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**GATE - 2009**

**Answer Keys**

<b>1</b>	B	<b>2</b>	C	<b>3</b>	A	<b>4</b>	D	<b>5</b>	B	<b>6</b>	D	<b>7</b>	A
<b>8</b>	A	<b>9</b>	B	<b>10</b>	D	<b>11</b>	D	<b>12</b>	B	<b>13</b>	A	<b>14</b>	C
<b>15</b>	B	<b>16</b>	C	<b>17</b>	C	<b>18</b>	D	<b>19</b>	B	<b>20</b>	C	<b>21</b>	D
<b>22</b>	C	<b>23</b>	A	<b>24</b>	A	<b>25</b>	D	<b>26</b>	C	<b>27</b>	D	<b>28</b>	D
<b>29</b>	B	<b>30</b>	C	<b>31</b>	C	<b>32</b>	A	<b>33</b>	A	<b>34</b>	B	<b>35</b>	B
<b>36</b>	A	<b>37</b>	A	<b>38</b>	C	<b>39</b>	A	<b>40</b>	D	<b>41</b>	D	<b>42</b>	C
<b>43</b>	A	<b>44</b>	C	<b>45</b>	A	<b>46</b>	C	<b>47</b>	B	<b>48</b>	C	<b>49</b>	A
<b>50</b>	A	<b>51</b>	B	<b>52</b>	C	<b>53</b>	D	<b>54</b>	A	<b>55</b>	C	<b>56</b>	B
<b>57</b>	A	<b>58</b>	A	<b>59</b>	B	<b>60</b>	D						

Q.1 (B)

Since all the applied voltage appears across it.

Q.2 (C)

Let  $y = \frac{u}{v}$ , % error in  $y =$  % error in  $u -$  % error in  $v$

Here  $u = G_1 + G_2$ ,  $v = G_3$

Q.3 (A)

When diode is ON,  $i = 1\text{mA}$ . When diode is OFF,  $i$  is zero after small reverse recovery time.

Q.6 (D)

Internal resistance =  $\frac{2000\text{V}}{400\text{A}} = 5\Omega$

Internal voltage drop =  $200\text{A} \times 5\Omega = 1000\text{V}$

Q.7 (A)

It is a balanced Wheatstone bridge.

Q.9 (B)

$P = \frac{EV}{X} \sin \delta \approx \frac{V^2}{X} \sin \delta$

Q.12 (B)

Q.13 (A)

All other XNOR, NOR, NAND gates can be derived from NOT, OR, AND gates.

Q.14 (C)

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$$M = \sqrt{L_1 L_2}; L_1 = \frac{N_1 \phi_1}{i_1}, \phi_1 = B_1 A_1$$

$$\therefore \boxed{M \propto \sqrt{A_1 A_2}} \quad \frac{M_1}{M_2} = \sqrt{\frac{2\theta \times 2\theta}{1\theta \times 1\theta}} = \sqrt{4} = 2$$

$$M_2 = \frac{M_1}{2}$$

Q.15 (B)

B is stable as slip  $\approx 1$

A is unstable as slip  $\approx 0$

Q.17 (C)

$a = 1.42$ ; GM = -20 log a

Since  $a > 1$ , GM will be negative and unstable

$$\text{Now, } G(j\omega)H(j\omega) = \frac{1 - j\omega T_1}{j\omega C(1 + j\omega T_2)}$$

(Assuming one pole in RHS plane)

$$\boxed{|G(j\omega)H(j\omega)|} = -90 - \tan^{-1} \omega T_1 - \tan^{-1} \omega T_2$$

$$\text{At } \omega=0, \boxed{|G(j\omega)H(j\omega)|} = -90$$

$$\text{At } \omega=\infty, \boxed{|G(j\omega)H(j\omega)|} = -270$$

Q.18 (D)

From Routh table,

The equation is

$$2s^3 + 4s^2 + 2s + 4 = 0$$

$$s^2 [4 + 2s] + [2s + 4] = 0$$

$$(s^2 + 1)(2s + 4) = 0$$

$$\boxed{s = \pm j = -0.5} \text{ LHS}$$

Q.19 (B)

Since at  $\omega=2$  and  $\omega=25$ , slope changes from 40dB/dec to -60dB/dec at both the value. So there are poles at  $\omega=2$  and  $\omega = 25$ .

Also at  $\omega=0.1$  slope is -40dB/dec.

$\therefore$  It means there are two poles at origin.

Hence the transfer function of the form,

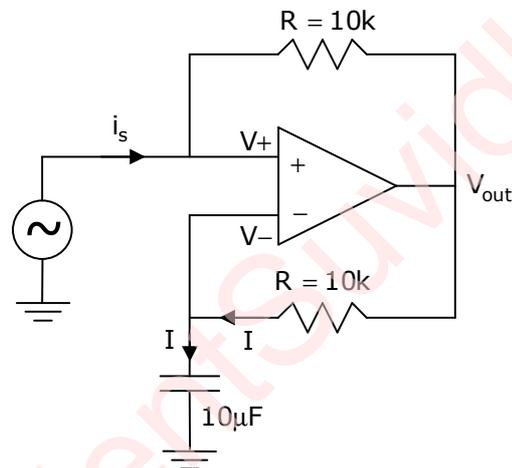
$$T(s) = \frac{K(s+5)}{s^2(s+2)(s+25)}$$

$$80 = 20 \log \frac{5k}{(0.1)^2 \times 50} \Rightarrow K = 1000$$

Q.20 (C)

Trace = Sum of principal diagonal elements

Q.21 (D)



$$X_c = \frac{1}{j\omega C} = \frac{1}{j2\pi \times 50 \times 10 \times 10^{-6}} = \frac{-j100}{\pi}$$

$$I = \frac{V_-}{X_c} = \frac{10}{X_c} = \frac{j\pi}{100}$$

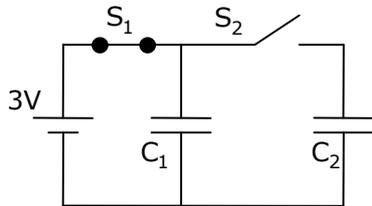
$$V_{out} = 10 + \frac{(10,000)j\pi}{100} = 10 + j100\pi$$

$$i_s = \frac{V_+ - V_{out}}{R} = \frac{10 - 10 - j100\pi}{10000} = -j10\pi \text{mA} = 10\pi \text{mA} \angle -90^\circ \text{s}$$

Q.22 (C)

When  $S_1$  is closed,  $S_2$  is open

$C_1$  is full charged to 3V

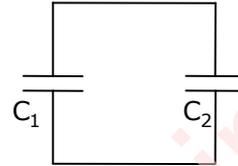


When  $S_1$  is open

$S_2$  is closed

$$Q = C_1 V_1 = C_2 V_2$$

$$1F \times 3V = 2F \times V_2; V_2 = 1.5V$$



Q.24 (A)

Apply KVL for input loop

$$V_{in} = (2k\Omega) I_1 + (49I_1 + I_1) / (100\mu F) s$$

$$= (2kI_1) + \frac{50I_1}{5 \times 100\mu F} = 2kI_1 + \frac{I_1}{(2\mu F) S}$$

$$C_{off} = 2\mu F$$

Q.25 (D)

XRA A  $\rightarrow$  Accumulator is cleared,  $A \leftarrow 00H$

MVI B  $\leftarrow$  FOH  $\rightarrow$  B  $\leftarrow$  FOH

SUB B  $\leftarrow$  (A)  $\leftarrow$  (A) - (B)

(A)  $\leftarrow$  FFFFFFF10H

Q.26 (C)

$$Y_{\text{Bus}} = \begin{bmatrix} Y_{11} & Y_{12} & Y_{13} & Y_{14} \\ Y_{21} & Y_{22} & Y_{23} & Y_{24} \\ Y_{31} & Y_{32} & Y_{33} & Y_{34} \\ Y_{41} & Y_{42} & Y_{43} & Y_{44} \end{bmatrix}$$

here

$$Y_{11} = Y_{10} + Y_{12} + Y_{13} + Y_{14} = -5j \quad \text{----- [1]}$$

$$Y_{22} = Y_{20} + Y_{22} + Y_{23} + Y_{24} = -10j \quad \text{----- [2]}$$

$$Y_{33} = Y_{30} + Y_{32} + Y_{33} + Y_{34} = -9j \quad \text{----- [3]}$$

$$Y_{44} = Y_{40} + Y_{42} + Y_{43} + Y_{44} = -8j \quad \text{----- [4]}$$

$$Y_{12} = Y_{21} = -Y_{12} = 2j$$

$$Y_{13} = Y_{31} = -Y_{13} = 2.5j$$

$$Y_{14} = Y_{41} = -Y_{14} = 0j$$

$$Y_{23} = Y_{32} = -Y_{23} = 2.5j$$

$$Y_{24} = Y_{42} = -Y_{24} = 4j$$

From equation 1,

$$Y_{10} = Y_{11} - Y_{12} - Y_{13} - Y_{14}$$

$$Y_{10} = -5j + 2j + 2.5j + 0j = -5j + 4.5j = -0.5j$$

From Eqn. 2

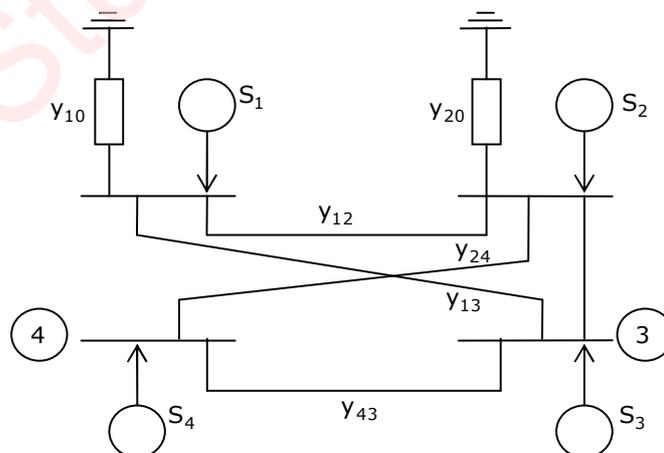
$$Y_{20} = Y_{22} - Y_{12} - Y_{23} - Y_{24} = -10j + 2j + 2.5j + 4j = -1.5j$$

From Eqn. 3

$$Y_{30} = Y_{33} - Y_{31} - Y_{32} - Y_{34} = -9j + 2.5j + 2.5j + j4 = 0$$

From Eqn. 4,

$$Y_{40} = Y_{44} - Y_{41} - Y_{42} - Y_{43} = -8j - 0 + 4j + j4 = 0$$



Q.28 (D)  $\checkmark$   
Phase crossover frequency

$$-90 - 0.1\omega \times \frac{180}{\pi} = -180$$

$$\therefore \omega = 15.7$$

$$a = |G(j\omega)|_{\omega=15.7}; GM = 20 \log a = 23.9 \text{ dB}$$

Q.32 (A)

$$G = \frac{P}{\cos \phi} = \frac{500 \text{ MW}}{0.9} = 555.56 \text{ MVA}$$

$$KE \text{ stored} = \frac{1}{2} \times M \times \left( \frac{2\pi N}{60} \right)^2 = \frac{1}{2} \times 27.5 \times 10^3 \left[ \frac{2\pi \times 3000}{60} \right]^2$$

$$= 1357.07 \text{ MJ}$$

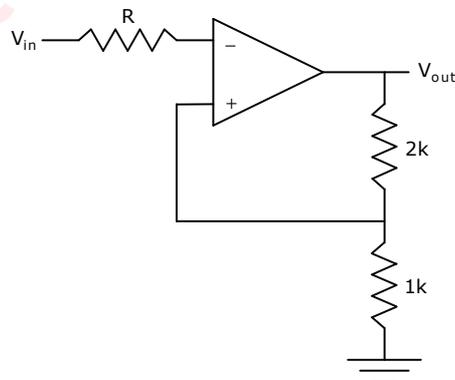
$$N = \frac{120f}{P} = 3000 \text{ rpm}$$

$$H = \frac{KE}{MVA} = \frac{1357.07}{555.56} = 2.44 \text{ MJ/MVA}$$

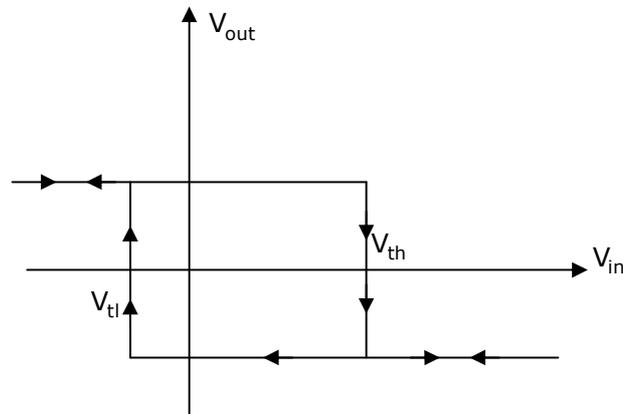
Q.40

<p><math>(0, 2) \rightarrow (2, 0)</math></p> <p><math>m = \frac{0 - 2}{2 - 0} = -1</math></p> <p><math>y - 2 = -1[x - 0] = -x</math></p> <p><span style="border: 1px solid black; padding: 2px;"><math>x + y = 2</math></span></p>	<p><math>\int_{(x,y)} F(x, y) dx dy</math></p> <p><math>= \int_0^2 x^2 + x(2 - x) dx + \int_2^0 y^2 + y(2 - y) dy = 0</math></p>
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Q.41 (D) For



Hysterisis Diagram is



$$\left. \begin{aligned} V_{th} &= \left(\frac{1k}{3k}\right) V_H = 2V = t_2 \\ V_{tl} &= \left(\frac{1k}{3k}\right) (-3) = -1V = t_4 \end{aligned} \right\} \begin{aligned} &\text{After } t_2, V_{out} = -3VA \\ &\text{After } t_4, V_{out} = 6VA \end{aligned}$$

Q.42 (C)

$$Z_{\text{auxiliary}} = r_a + j\omega L_a = 1 + j \times 2\pi \times 50 \times \frac{10}{\pi} = 1 + j1000$$

$$Z_{\text{main}} = r_m + j\omega L_m = 0.1 + j2\pi \times 50 \times \frac{0.1}{\pi} = 0.1 + j10 \approx 10 \angle 90^\circ$$

$$\text{starting torque} = KI_a I_m \sin(I_a, I_m) \rightarrow \sin(0) = 0$$

Q.43 (A)

$$V_L = L \frac{di}{dt}; \quad i = \frac{1}{L} \int V dt$$

$$i = \left[ \frac{\pi}{0.1} \right] \int 10 \sin 100\pi t = (100\pi) \frac{\cos 100\pi t}{100\pi}$$

$$i(t) = \cos 100\pi t$$

$$i(t) = 0 \text{ when } \cos 100\pi t = 0 \Rightarrow 100\pi t = n \frac{\pi}{2}$$

$$t = \frac{n}{200}$$

When  $n=1$ ,  $t=5\text{msec}$ ;  $n=2$ ,  $t=10\text{msec}$ ;  $n=3$ ,  $t=15\text{msec}$

$\therefore$  Answer is (A)

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Q.47 (B)

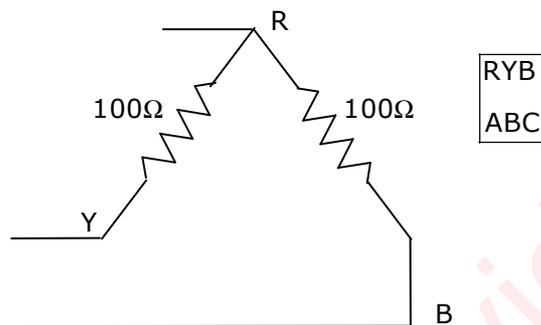
By Superposition theorem,

When 4V is shorted,  $i^1=0$ , as all the current will flow through short. When 5A is open,  $i^{11}=2A$

Therefore  $i_{2\Omega}=2A$

Q.48 (C)

Wattmeter reading = Current through the coil (I) × Voltage across Pressure coil (V) × Cos(phase angle between V & I)



$$I_{BR} = I_{CC} = \frac{400 \angle 120}{100} = 4 \angle 120$$

$$V_{YB} = V_{PC} = 400 \angle -120$$

$$W = 4 \angle -120 \times 400 \angle -120 \times \cos(240) = -800W$$

Q.49 (A)

For triangular wave,

$$\text{Avg value} \rightarrow \frac{V_m}{3}$$

$$\text{rms value} \rightarrow \frac{V_m}{\sqrt{3}}$$

$$\therefore \frac{V_m}{3} = 10V, V_m = 30V$$

$$\text{rms value} = \frac{30}{\sqrt{3}} = 10\sqrt{3}$$

Q.53 (D)

Q.54 (A)

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$$V = L \frac{di'}{dt'} = \left( \frac{400}{\pi} \text{ m} \right) \frac{dt}{dt'}$$

$$\frac{dt}{dt'} \text{ is max } \rightarrow 0 \rightarrow 5 \text{ msec}$$

$$V = \left( \frac{400}{\pi} \text{ m} \right) \frac{10}{5 \text{ msec}} \left[ \frac{800}{\pi} \right] \text{ V}$$

$$\text{If } i(t) = 10 \sin(100\pi t)$$

$$V = \left( \frac{400}{\pi} \right)^{\text{mH}} \frac{di(t)}{dt} = \left[ \frac{400}{\pi} \right] \pi \times 10 \times \cos(100\pi t)$$

$$= 400 \cos(100\pi t)$$

$$V_{\text{max}} = 400 \text{ V}$$

Q.55 (C)

$$\frac{dx_1(t)}{dt} = -3x_1(t) + x_2(t) + 2\mu(t)$$

$$\Rightarrow s x_1(s) = -3x_1(s) + x_2(s) + 2 \text{ ----- [1]}$$

$$\frac{dx_2(t)}{dt} = -2x_2(t) + \mu(t)$$

$$\Rightarrow s x_2(s) = -2x_2(s) + 1$$

$$(s+2)x_2 = 1$$

$$x_2 = \frac{1}{(s+2)}; \text{ From [1], } (s+3)x_1 = 2 + \frac{1}{s(s+2)}$$

$$x_1 = \frac{2s+5}{(s+2)(s+3)}$$

$$y(t) = x_1(t) \Rightarrow H(s) = \frac{Y(s)}{X(s)} = \frac{2s+5}{(s+2)(s+3)} = \frac{2s+5}{s^2+5s+6}$$

Q.56 (B)

$$e^{At} = L^{-1}[\phi(s)]; \phi(s) = \left[ [sI-A]^{-1} \right]$$

From given state equations

$$\dot{x}_1(t) = -3x_1(t) + x_2(t) + 2\mu(t)$$

$$\dot{x}_2(t) = -2x_2(t) + \mu(t)$$

$$\phi(s) = \left[ \begin{bmatrix} s & 0 \\ 0 & s \end{bmatrix} - \begin{bmatrix} -3 & 1 \\ 0 & -2 \end{bmatrix} \right]^{-1} = \left[ \begin{bmatrix} s+3 & -1 \\ 0 & s+2 \end{bmatrix} \right]^{-1}$$

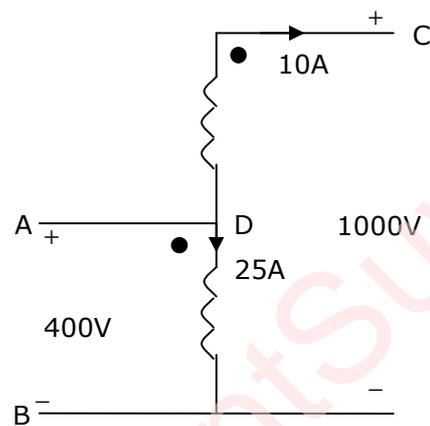
$$= \frac{1}{(s+2)(s+3)} \begin{bmatrix} s+2 & 1 \\ 0 & s+3 \end{bmatrix}$$

$$\phi(s) = \begin{bmatrix} \frac{1}{s+3} & \frac{1}{(s+2)(s+3)} \\ 0 & \frac{1}{(s+2)} \end{bmatrix}$$

$$e^{At} = L^{-1}[\phi(s)] = \begin{bmatrix} e^{-3t} & e^{-2t} - e^{-3t} \\ 0 & e^{-2t} \end{bmatrix}$$

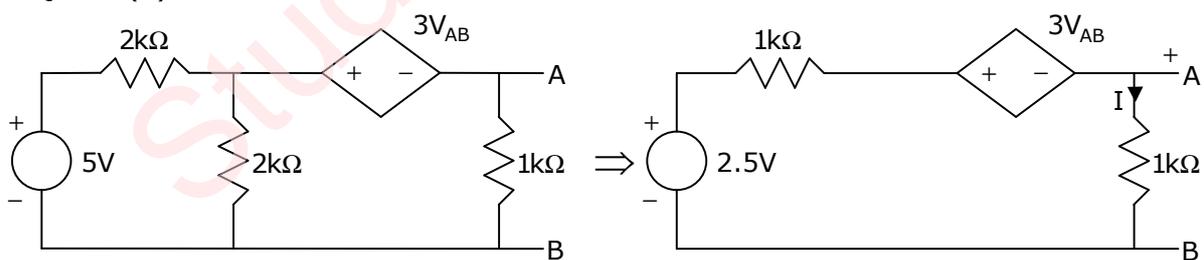
Q.57 (A)

Q.58 (A)



$$1000 = 25A + 400V = 10A \times 1000V$$

Q.59 (B)



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$$V_{OC} = V_{AB}$$

$$2.5 = (1k\Omega)I + 3V_{AB} + V_{AB}$$

$$V_{AB} = (1k\Omega)I$$

$$\therefore 2.5 = V_{AB} + 3V_{AB} + V_{AB} = 5V_{AB}$$

$$V_{AB} = 0.5V$$

Apply short across AB:  $V_{AB} = 0$ ,  $3V_{AB} = 0$ ,

$$I_{sc} = \frac{2.5V}{1k\Omega} = 2.5mA$$

Q.60 (D)

$$R_{th} = \frac{V_{oc}}{I_{sc}} = \frac{0.5V}{2.5mA} = \frac{1000}{5} = 200\Omega = 0.2k\Omega$$