Printed Pages: 4 managed government

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BT-6/M12

DIGITAL SIGNAL PROCESSING

Paper-ECE-306-E

Time allowed: 3 hours!

[Maximum marks: 100]

impulse pan

Unit-I Dog to be add

1. (a) Determine the causal signal x (n) if its z-transform X(z) is given by:

$$X(z) = \frac{1}{4} \frac{(1+6z^{-1}+z^{-2})}{(1-2z^{-1}+2z^{-2})(1-\frac{1}{2}z^{-1})}$$

(b) If X (z) is the z-transform of x (n), show that if

$$x_{k}(n) = \begin{cases} x\left(\frac{n}{k}\right), & \text{if } \frac{n}{k} \text{ integer} \\ 0, & \text{otherwise} \end{cases}$$

then
$$X_{\nu}(Z) = X(Z^k)$$

8

(c) Determine the convolution of following pairs of signals by means of z-transform

$$x_{i}(n) = nu(n)$$

$$x_2(n) = (2^n) u(n-1)$$

7

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[P.T.O.

4. (a) Consider the system described by the difference

$$y(n) = a y(n-1) - a x(n) + x(n-1)$$

(i) Show that it is all-pass.

5

- (ii) Obtain the direct form II realization of the system.
- (b) Consider a causal IIR system with the system function

$$H(z) = \frac{1+2z^{-1}+3z^{-2}+2z^{-3}}{1+0.9z^{-1}-0.8z^{-2}+0.5z^{-3}}$$

Determine the equivalent lattice-ladder structure. 10

Unit-III

5. (a) Design an FIR linear-phase, digital filter approximating the ideal frequency response

$$H_{d}(w) = \begin{cases} 1 & \text{for } |w| \le \frac{\pi}{6} \\ 0 & \text{for } \frac{\pi}{6} < |w| \le \pi \end{cases}$$

- filter based on window method with a rectangular window.
- (ii) Repeat part (i) using Hamming window.

3

(b) Explain the Gibbs phenomenon with example.

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[P.T.O.

- 6. (a) Write a short note on "Alternation theorem". 10
 - (b) Determine the unit sample response {h (n)} of a linear-phase FIR filter of length M = Y for which the frequency response at w = 0 and

$$w = \frac{\pi}{2}$$
 is specified as $H_r(0) = 1$, $H_r(\frac{\pi}{2}) = \frac{1}{2}$.

Consider a caus VI find cm with the system function

- 7. Explain the design of digital filters based on least square's methods.
- 8. A digital low-pass filter is required to meet the following specifications:

Passband Ripple : ≤ 1 dB

Passband Edge: 4 KHz

Stopband attenuation: ≥ 40 dB

Stopband edge: 6 KHz

Sample Rate: 24 KHz; Assume t = 1

The filter is to be designed by performing a bilinear transformation on an analog system function. Determine what order Butterworth, Chebyshev and Elliptic analog designs must be used to meet the specifications in the digital implementation.

6+6+8