SnS_2009_1

Roll No.

Total No. of Pages: 3

BT-4/M09

9331

Signal and System

Paper: EE-208-E

Time: Three Hours]

[Maximum Marks: 100

Note :- Attempt any FIVE questions.

UNIT-I

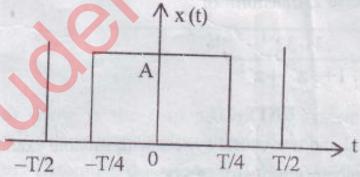
- 1. (a) Explain periodic and aperiodic signals with examples.
 - (b) Determine whether the following signal is periodic or not?

$$x(t) = \sin \sqrt{2} \Pi t$$
.

(c) Determine the even and odd components of each of the following signal:

$$x(t) = 1 + t + 2t^2 + 5t^3 + 8t^4.$$

- (d) Given a complex-valued exponential signal $x(t) = Ae^{\alpha t + jwt}$ for $\alpha > 0$.
- (a) Enumerate what are the Drichlet's conditions. Following fig. shows the peridic rectangular waveform. Obtain its Fourier Series representation.



(b) A damped sine wave is expressed as :

$$x(t) = e^{-at} sinwt$$

Obtain Laplace transform of the signal.

UNIT-II

 (a) Explain and define cumulative distribution function (CDF) and explain its various properties. Also determine whether the following function is CDF:

$$F_{x}(x) = \begin{cases} 0 \text{ for } x < a, \\ 1/2(x/a+1) \text{ for } -a \le x \le a \\ 1 \text{ for } x > a \end{cases}$$

(b) A joint probability density function of two random variables X and Y is given as:

$$f_{xy}(x,y) = \begin{cases} e^{-(x+y)} \text{ for } x \ge 0, y \ge 0 \\ 0 \text{ otherwise} \end{cases}$$

determine the following:

- (i) P(X < 1)
- (ii) P(X > Y)
- (iii) P (X+Y < 1).
- (a) State and explain sampling theorem for continuous-time signals.
 Also discuss zero order and first order field. Also explain what is meant by Aliasing.
 - (b) Find the inverse Z-transform of:

$$X(z) = \frac{1 - 32^{-1}}{1 + \frac{3}{5}z^{-1} + z^{-2}}$$

UNIT-III

- (a) Explain causal and non causal system with suitable examples.
- (b) Explain the memory property of systems.
- (c) Test the following system for linearity, time-in variance and casuality.
 - (i) a(n) = b(-n + 5)
 - (ii) $a(n) = b(n) \sin(w_0 n)$

SnS_2009_3

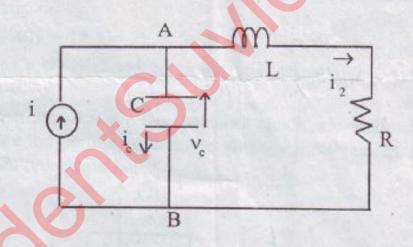
6. (a) Given a continuous-time (LTI) system with unit impulse response h (t). A continuous-time signal x(t) is applied to the input of this LTI system where:

$$x[t] = e^{-at}$$
. $u[t]$ for $a > 0$
and $h(t) = u(t)$. Evaluate the output $y(t)$.

(b) Write a Technical note on SIMO and MIMO system.

UNIT-IV

- (a) Explain what is meant by State, State Variables and State Vectors.
 Discuss the State-Variable representation of an LTI system.
 Also explain the advantage of State Space method over traditional representation method.
 - (b) Consider the network shown in fig. below. Obtain the state equation of the system.



- 8. (a) How is the response of LTI system determined for the deterministic and stochastic signal?
 - (b) Determine the response y(n) ≥ 0 of the system described by the following difference equation. Also draw its state diagram.

$$y(n) - 2y(n-2) + 4y(n-2) = x(n) + 2 - 4x(n-1)$$

to the input $x[n] = 2^n u(n)$.