Seat No.: Enrolmen

GUJARAT TECHNOLOGICAL UNIVERSITY

BE - SEMESTER-VII • EXAMINATION - WINTER • 2014

	•	Code: 1/1903 Date: 04-12-2014	4
Ti	-	Name: Computer Integrated Manufacturing 0:30 am - 01:00 pm Total Marks: 70 ns:	0
	1. 2. 3.	Make suitable assumptions wherever necessary.	
Q.1	(a)	Classify CNC machine tools on the basis of : (i) Type of feedback system (ii) Type of tool motion control	07
	(b)	What is FMS? Explain any three flexibilities associated with FMS.	07
Q.2	(a) (b)	What is tool compensation? Explain tool length and cutter radius compensation. Explain the feedback system of NC/CNC machine. OR	07 07
	(b)	What do you mean by geometry statement in ATP? Explain with suitable example, the format of geometry statements.	07
Q.3	(a)	Write complete part program for the component shown in Fig.1. Raw material: MS Φ 30 X 65 mm, cutting speed V= 40 m/min and feed=0.1 mm/rev	07
	(b)	What is GT? Explain methods of grouping parts into part families in brief. OR	07
Q.3	(a)	What are the objectives of cellular manufacturing? Explain the different types of machine cell designs.	07
	(b)	What are the objectives of FMS? Describe the various layouts used in FMS.	07
Q.4	(a)	Sketch and explain cylindrical and SCARA configuration of industrial robot, showing work envelope.	07
	(b)	What are the different types of gripper used in robot? Explain any two in detail.	07
0.4		OR	
Q.4	(a) (b)	Enlist and explain different elements of a robot. Which parameters are to be considered for robot specification and selection of robot? Explain in details.	07 07
Q.5	(a) (b)	Discuss the concept of CIM wheel and state potential benefits of CIM. Distinguish between variant and generative type CAPP stating their advantages. OR	07 07
Q.5	(a) (b)	Explain MRP-I and MRP-II in detail. Explain in brief Programmable Logic Controllers	07 07

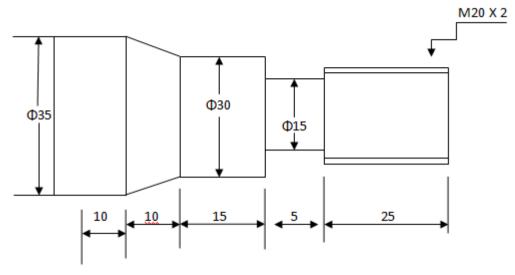


FIG. 1 (Q. No.3 (a))

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