

## FIRST SEMESTER EXAMINATION, 2009-10

## MATHEMATICS-I

Time: 3 Hours

Total Marks: 100

## Section-A

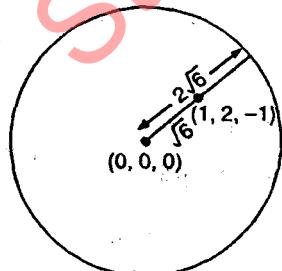
All parts of this question are compulsory.

 $(2 \times 10) = 20$ 

**Q.1. (a)** If  $f(x) = f(0) + k f_1(0) + \frac{k^2}{L^2} f_2(0) k$ ,  
 $0 < \theta < 1$  then the value of  $\theta$  when  $k = 1$  and  $f(x) = (1-x)^{5/2}$  is given as .....

Ans.

**Q.1. (b)** The short distance from the point  $(1, 2, -1)$  to the sphere  $x^2 + y^2 + z^2 = 24$  shall be .....

Ans.  $\sqrt{6}$ Justification : Given point  $= (1, 2, -1)$ Given sphere is  $x^2 + y^2 + z^2 = 24$ Centre of given sphere is  $(0, 0, 0)$ Its radius  $= \sqrt{24} = 2\sqrt{6}$ Distance of  $(0, 0, 0)$  to  $(1, 2, -1)$  is

$$\begin{aligned} d &= \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2 + (z_1 - z_2)^2} \\ &= \sqrt{(1-0)^2 + (2-0)^2 + (-1-0)^2} \\ &= \sqrt{1+4+1} = \sqrt{6} \end{aligned}$$

$\therefore$  distance from centre is less than radius.

$\therefore$  Point lies inside the sphere.

$\therefore$  Distance from surface = Radius – Distance from  
 centre  $= 2\sqrt{6} - \sqrt{6} = \sqrt{6}$

**Q.1. (c)** The jacobian  $J\left(\frac{u, v}{x, y}\right)$  for  $u = e^x \sin y$ ,

$v = x \log \sin y$  shall be .....

Ans.  $e^x \cos y (x - \log \sin y)$ 

$$\text{Justification : } J\left(\frac{u, v}{x, y}\right) = \begin{vmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{vmatrix}$$

$$= \begin{vmatrix} e^x \sin y & e^x \cos y \\ \log \sin y & x \frac{\cos y}{\sin y} \end{vmatrix}$$

$$\Rightarrow J\left(\frac{u, v}{x, y}\right) = xe^x \cos y - e^x \cos y \log \sin y$$

$$= e^x \cos y (x - \log \sin y)$$

**Q.1. (d)** For the curve  $ay^2 = x^2(a-x)$ , which of the following statement(s) is/are Incorrect?

- (i) Curve passes through origin
- (ii) Curve is symmetrical about y-axis
- (iii) Curve has two branches
- (iv) Curve has no tangents at origin

Ans. (i) Correct

(ii) In correct

(ii) Correct

(iv) In Correct

Q.1. (e) If  $P$  and  $Q$  are non-singular matrices then for Matrix  $M$ , which of the following statements are correct?

- (i) Rank  $(PMQ) > \text{Rank } M$
- (ii) Rank  $(PMQ) = \text{Rank } M$
- (iii) Rank  $(PMQ) < \text{Rank } M$
- (iv) Rank  $(PMQ) > \text{Rank } M + \text{Rank } (PQ)$

Ans. (i) In Correct

(ii) Correct

(iii) In Correct

(iv) In Correct

Q.1. (f) If  $\lambda$  is an eigen value of the matrix ' $M$ ' then for the matrix  $(M - \lambda I)$ , which of the following statement(s) is/are correct?

- (i) Skew symmetric
- (ii) Non singular
- (iii) Singular
- (iv) None of these

Indicate True/False for the following statements

Ans. (i) In Correct

(ii) In Correct

(iii) Correct

(iv) In Correct

Q. 1. (g) For  $\int\limits_0^{\infty} \int\limits_x^{\infty} f(x, y) dx dy$ , the change of order of integration is

(i)  $\int\limits_0^{\infty} \int\limits_x^{\infty} f(x, y) dx dy$ , True/False

(ii)  $\int\limits_{x=0}^{\infty} \int\limits_0^{\infty} f(x, y) dx dy$ , True/False

(iii)  $\int\limits_0^{\infty} \int\limits_0^y f(x, y) dx dy$ , True/False

(iv)  $\int\limits_0^{\infty} \int\limits_0^x f(x, y) dx dy$ , True/False

Ans. (i) In Correct

(ii) In Correct

(iii) Correct

(iv) In Correct

Justification: Given integral  $I = \int\limits_0^{\infty} \int\limits_x^{\infty} f(x, y) dx dy$

Region of integration is shown in Figure:  
Changing the order of integration. We take strip parallel to x axis.

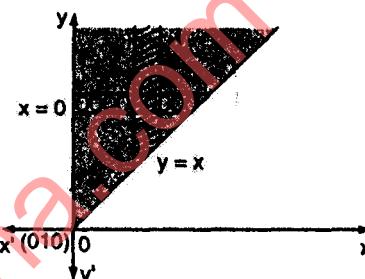


Fig.

Now, sin u' are  
 $x$  varies from 0 to  $y$   
 $y$  varies from 0 to  $\infty$

$$\therefore \int\limits_0^{\infty} \int\limits_x^{\infty} f(x, y) dy dx = \int\limits_{y=0}^{\infty} \int\limits_{x=0}^y f(x, y) dx dy$$

Q.1. (h) The value of  $\left| -\frac{1}{2} \right|$  is given by

(i)  $\sqrt{\pi}$ , True/False

(ii)  $2\sqrt{\pi}$ , True/False

(iii)  $-\sqrt{\pi}$ , True/False

(iv)  $-2\sqrt{\pi}$ , True/False

Pick up the correct option from the following:

Ans. (i) In Correct

(ii) In Correct

(iii) In Correct

(iv) Correct

Justification :  $\lceil n+1 \rceil = n \lceil n \rceil$

$$\Rightarrow \lceil n = \frac{\lceil n+1 \rceil}{n}$$

$$\Rightarrow \frac{\lceil n+1 \rceil}{2} = \frac{\lceil \frac{n+1}{2} + 1 \rceil}{2} = \left[ \text{Putting } n = -\frac{1}{2} \right]$$

$$\Rightarrow \frac{\lceil \frac{1}{2} \rceil}{2} = \frac{\lceil \frac{1}{2} + 1 \rceil}{2}$$

$$= -2 \lceil \pi \rceil \quad \left[ \left| \frac{1}{2} \right| = \sqrt{\pi} \right]$$

$$ax + 4y - 5z = 4$$

(i) No solution

(ii) A unique solution

(iii) Infinite no. of solutions

**Ans.** Given system is

$$3x + 5y - az = 7$$

$$x + by + 4z = -3$$

$$ax + 4y - 5z = 4$$

Augmented matrix  $[A : B]$

$$= \begin{bmatrix} 3 & 5 & -a & : & 7 \\ 1 & -b & 4 & : & -3 \\ a & 4 & -5 & : & 4 \end{bmatrix}$$

Which is not reducible to Conclude form

*∴ Given question is wrong.*

**Q.2. (b)** Find the value of  $D^n \{x^{n-1} \log x\}$ ,

$$D^n \equiv \frac{d^n}{dx^n}$$

**Ans.** We want to find  $D^n \{x^{n-1} \log x\}$

$$\text{let, } y = x^{n-1} \log x$$

Differentiating (1) w.r.t x, we get,

$$y_1 = (n-1)x^{n-2} \log x + x^{n-1} \frac{1}{x}$$

$$\Rightarrow xy_1 = (n-1)x^{n-1} \log x + x^{n-1}$$

$$\Rightarrow xy_1 = (n-1)y + x^{n-1}$$

$$[x^{n-1} \log x = y]$$

Differentiating (2)  $n-1$  times by labinitz's theorem,

$$= [xy_n + {}^{n-1}C_1 (1) y_{n-1}]$$

$$= (n-1)y_{n-1} + \frac{d^{n-1}}{dx^{n-1}} (x^{n-1})$$

$$\Rightarrow xy_n + (n-1)y_{n-1} = (n-1)y_{n-1} + \frac{d^{n-1}}{dx^{n-1}} (x^{n-1})$$

$$\left[ \because r_1 = r \right. \\ \left. {}^{n-1}C_1 = n-1 \right]$$

$$\Rightarrow xy_n = \frac{d^{n-1}}{dx^{n-1}} (x^{n-1})$$

**Q.1. (i)** If  $\vec{F}$  is the velocity of a fluid particle then

$$\int_C \vec{F} \cdot d\vec{r} \text{ represents}$$

- (i) Work done
- (ii) Circulation
- (iii) Flux
- (iv) Conservative field

**Ans.** Work done

**Q. 1. (j)** The value of  $\iint_S \vec{F} \cdot \vec{n} d\vec{s}$ , where

$\vec{F} = ax \hat{i} + by \hat{j} + cz \hat{k}$ ; a, b, c being constants is given by

$$(i) \frac{\pi}{3} (a+b+c)$$

$$(ii) \frac{4\pi}{3} (a+b+c)$$

$$(iii) 2\pi (a+b+c)$$

$$(iv) \pi (a+b+c)$$

**Ans.** The given question is wrong as surface is not given.

## Section-B

Attempt any three parts of the following :

$$(10 \times 3) = 30$$

**Q.2. (a)** Determine the values of 'a' and 'b' for which the following system of equations has

$$3x + 5y - az = 7,$$

$$x - by + 4z = -3,$$

$$\Rightarrow xy_n = (n-1)!$$

$$\left[ \because \frac{d^n}{dx^n} (x^n) = n! \right]$$

$$\Rightarrow y_n = \frac{(n-1)!}{x}$$

$$D^n (x^{n-1} \log x) = \frac{(n-1)!}{x} \quad \text{Ans.}$$

$$\text{Q.2. (c)} \text{ If } u = \frac{(x+y)}{z}, \ v = \frac{(y+z)}{x},$$

$$w = \frac{y(x+y+z)}{(xz)}$$

then show that  $u, v, w$  are not independent and find the relation between them.

$$\text{Ans. Here, } u = \frac{x+y}{z},$$

$$v = \frac{y+z}{x},$$

$$w = \frac{y(x+y+z)}{xz}$$

B show that,  $z, y, x$  and  $w$  are not independent, we

$$\text{shall show that } \frac{\partial(u, v, w)}{\partial(x, y, z)} = 0$$

Now,

$$\frac{\partial u}{\partial x} = \frac{\partial}{\partial x} \left( \frac{x+y}{z} \right) = \frac{1}{2}$$

$$\frac{\partial u}{\partial y} = \frac{\partial}{\partial y} \left( \frac{x+y}{z} \right) = \frac{1}{2}$$

$$\begin{aligned} \frac{\partial u}{\partial z} &= \frac{\partial}{\partial z} \left( \frac{x+y}{z} \right) = (x+y) \frac{d}{dz} \left( \frac{1}{z} \right) \\ &= -\frac{(x+y)}{z^2} \end{aligned}$$

$$\frac{\partial v}{\partial x} = \frac{\partial}{\partial x} \left( \frac{y+z}{x} \right) = y+z \frac{\partial}{\partial x} \left( \frac{1}{x} \right) = -\frac{(x+y)}{z^2}$$

$$\frac{\partial v}{\partial y} = \frac{\partial}{\partial y} \left( \frac{y+z}{x} \right) = \frac{1}{x}$$

$$\frac{\partial v}{\partial z} = \frac{\partial}{\partial z} \left( \frac{y+z}{x} \right) = \frac{1}{x}$$

$$\frac{\partial w}{\partial x} = \frac{\partial}{\partial x} \left[ \frac{y(x+y+z)}{xz} \right] = \frac{y}{z} \frac{\partial}{\partial x} \left[ \frac{x+y+z}{x} \right]$$

$$= \frac{y}{z} \frac{\partial}{\partial x} \left[ 1 + \frac{y+z}{x} \right]$$

$$= \frac{y}{z} \left[ -\left( \frac{y+z}{x^2} \right) \right]$$

$$= \frac{-y(y+z)}{x^2 z}$$

$$= \frac{\partial w}{\partial y} = \frac{\partial}{\partial y} \left[ \frac{y(x+y+z)}{xz} \right]$$

$$= \frac{1}{xz} \frac{2}{\partial y} [y(x+y+z)]$$

$$\Rightarrow \frac{\partial w}{\partial y} = \frac{1}{xz} [x+2y+z] = \frac{x+2y+z}{xz}$$

$$\frac{\partial w}{\partial z} = \frac{\partial}{\partial z} \left[ \frac{y(x+y+z)}{xz} \right]$$

$$= \frac{y}{x} \frac{\partial}{\partial z} \left[ \frac{x+y}{z} + 1 \right]$$

$$= \frac{-y(x+y)}{xz^2}$$

$$\therefore \frac{\partial(u, v, w)}{\partial(x, y, z)} = \begin{vmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} & \frac{\partial u}{\partial z} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} & \frac{\partial v}{\partial z} \\ \frac{\partial w}{\partial x} & \frac{\partial w}{\partial y} & \frac{\partial w}{\partial z} \end{vmatrix}$$

$$= \begin{vmatrix} \frac{1}{2} & \frac{1}{2} & -\frac{(x+y)}{z^2} \\ \frac{-y(z)}{x^2} & \frac{1}{x} & \frac{1}{x} \\ \frac{-y(y+z)}{x^2 z} & \frac{x+2y+z}{xz} & -\frac{y(x+y)}{xz^2} \end{vmatrix}$$

Taking  $\frac{1}{2}$ ,  $\frac{1}{x^2}$  and  $\frac{1}{x^2 z^2}$  common from  $R_1, R_2$  and  $R_3$  respectively, we get,

$$\frac{\partial(u, v, w)}{\partial(x, y, z)} = \frac{1}{z^2 x^2} \times \frac{1}{x^2 z^2} \times \frac{1}{x^2} = \frac{1}{x^5 z^5}$$

$$\begin{vmatrix}
 z & z & -(x+y) \\
 -(y+z) & x & x \\
 -yz(y+z) & xz(x+2y+z) & -xy(x+y)
 \end{vmatrix} = \frac{1}{x^4 z^4} \begin{vmatrix}
 1 & 1 & -(x+y) \\
 -1 & 0 & x \\
 y(x-z) & x(y+z) & -xy(x+y)
 \end{vmatrix}$$

$$\begin{vmatrix}
 x+y+z & x+y+z & 0 \\
 -(x+y+z) & 0 & xz(x+2y+z) \\
 xy(x+y) - yz(y+z) & +xy(x+y) & -(x+y) \\
 & x & -xy(x+y)
 \end{vmatrix} = \frac{(x+y+z)^2}{x^4 z^4} \begin{vmatrix}
 0 & 1 & -y \\
 -1 & 0 & x \\
 y(x-z) & x(y+z) & xy(x+y)
 \end{vmatrix}$$

Applying  $R_1 \rightarrow R_1 + R_2$

$$= \frac{(x+y+z)^2}{x^4 z^4} [0 - 1\{xy(x+y) - xy(x-z)\} - y\{-x(y+z)\}]$$

$$= \frac{(x+y+z)^2}{x^4 z^4} [-xy(x+y) + xy(x-z) + xy(y+z)]$$

$$= \frac{(x+y+z)^2 \cdot xy}{x^4 z^4} [-x-y+x-z+y+z] = 0$$

$$\Rightarrow \frac{\partial(u, v, w)}{\partial(x, y, z)} = 0$$

*Given function u, v and w are not independent*

**2nd part:** To find the relation,  
we calculate uv

$$\begin{aligned}
 \text{Now, } uv &= \frac{x+y}{z} \cdot \frac{y+z}{x} \left[ \because u = \frac{x+y}{z}, v = \frac{y+z}{x} \right] \\
 &= \frac{(x+y)(y+z)}{xz} = \frac{xy + xz + y^2 + yz}{xz} \\
 &= \frac{y(x+y+z)}{xz} + \frac{xz}{xz} \\
 &= w + 1 \quad \left[ \because w = \frac{y(x+y+z)}{xz} \right]
 \end{aligned}$$

Thus,  $uv = 2w + 1$ , which is desired relation.

**Q.2. (d)** A rigid body is rotating with constant angular velocity  $\omega$  about a fixed axis. If 'v' is the linear velocity of any point of the body then prove that  $\text{curl } v = 2\omega$ .

**Ans.** Here, angular velocity of the body =  $\vec{\omega}$

Linear velocity of the body =  $\vec{v}$

$$\text{Let } \vec{w} = \omega_1 \hat{i} + \omega_2 \hat{j} + \omega_3 \hat{k}$$

We know that

$$\begin{aligned}
 \text{Now, } xy(x+y) - yz(y+z) &= y[x(x+y) - z(y+z)] \\
 &= y(x^2 + xy - yz - z^2) \\
 &= y[x^2 - z^2 + xy + yz - yz] \\
 &= y[(x+z)(x-z) + y(x-z)] \\
 &= y[(x-z)(x+y+z)] \\
 &= y(x-z)(x+y+z)
 \end{aligned}$$

$$\begin{aligned}
 \text{Also, } xz(x+2y+z) + xy(x+y) &= x[zx + 2yz + z^2 + xy + y^2] \\
 &= x[y^2 + z^2 + 2yz + zx + xy] \\
 &= x[(y+z)^2 + x(y+z)] \\
 &= x(y+z)(x+y+z)
 \end{aligned}$$

Putting these values in  $\frac{\partial(u, v, w)}{\partial(x, y, z)}$  we get,

$$\frac{\partial(u, v, w)}{\partial(x, y, z)} = \frac{1}{x^4 z^4}$$

$$\begin{vmatrix}
 x+y+z & x+y+z & -(x+y) \\
 -(x+y+z) & 0 & x \\
 y(x-z)(x+y+z) & x(y+z)(x+y+z) & -xy(x+y)
 \end{vmatrix}$$

Taking  $x+y+z$  common from  $C_1$  as well as from  $C_2$  we get,

$$\frac{\partial(u, v, w)}{\partial(x, y, z)} = \frac{(x+y+z)^2}{x^4 z^4}$$

$$\begin{vmatrix}
 1 & 1 & -(x+y) \\
 -1 & 0 & x \\
 y(x-z) & x(y+z) & -xy(x+y)
 \end{vmatrix}$$

$$\begin{aligned}\vec{v} &= \vec{\omega} \times \vec{r} \\ &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ w_1 & w_2 & w_3 \\ x & y & z \end{vmatrix} [\because \vec{r} = xi + yj + zk] \\ &= \hat{i}(w_2z - w_3y) - \hat{j}(w_1z - w_3x) + \hat{k}(w_1y - w_2x)\end{aligned}$$

Now,

$$\text{Curel } \vec{v} = v + \vec{v}$$

$$\begin{aligned}&= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ w_2z - w_3y & w_3x - w_1z & w_1y - w_2x \end{vmatrix} \\ &= \hat{i}[w_1 + w_1] - \hat{j}[-w_2 - w_2] + \hat{k}[w_3 + w_3] \\ &= 2(w_1\hat{i} + w_2\hat{j} + w_3\hat{k}) \\ \Rightarrow \text{Curel } \vec{v} &= 2\bar{w} \quad [\because \bar{w} = w_1\hat{i} + w_2\hat{j} + w_3\hat{k}] \quad \text{Ans.}\end{aligned}$$

Q. 2. (e) Assuming  $\sqrt{n}\sqrt{1-n} = \pi \operatorname{cosec} n\pi, 0 < n < 1$ ,

$$\text{show that } \int_0^\infty \frac{x^{p-1}}{1+x} dx = \left( \frac{\pi}{\sin p\pi} \right), 0 < p < 1$$

Ans. Given that  $\sqrt{n}\sqrt{1-n} = \pi \operatorname{cosec} n\pi$

To show

$$\text{We know that, } B(p, q) = \int_0^\infty \frac{x^{p-1}}{(1+x)^{p+q}} dx$$

$$\Rightarrow \frac{\sqrt{p}\sqrt{q}}{\sqrt{p+q}} = \int_0^\infty \frac{x^{p-1}}{(1+x)^{p+q}} dx$$

$$\left[ \because B(m, n) = \frac{\sqrt{m}\sqrt{n}}{\sqrt{m+n}} \right]$$

$$\Rightarrow \frac{\sqrt{p}\sqrt{1-p}}{\sqrt{p+1-p}} = \int_0^\infty \frac{x^{p-1} dx}{(1+x)^{p+1-p}} \quad [\text{Putting } q = 1-p]$$

$$\Rightarrow \frac{\sqrt{p}\sqrt{1-p}}{\sqrt{1}} = \int_0^\infty \frac{x^{p-1}}{1+x} dx$$

$$\Rightarrow \sqrt{p}\sqrt{1-p} = \int_0^\infty \frac{x^{p-1}}{1+x} dx \quad [\because \pi = 1]$$

$$\Rightarrow \pi \operatorname{cosec} p\pi = \int_0^\infty \frac{x^{p-1}}{1+x} dx$$

$[\because \sqrt{n}\sqrt{1-n} = \pi \operatorname{cosec} n\pi]$

$$\int_0^\infty \frac{x^{p-1}}{1+x} dx = \frac{\pi}{\sin p\pi} \quad \text{Ans.}$$

## Section-C

All questions of this section are compulsory.  
Attempt any two parts from each question :

$(10 \times 5) = 50$

Q. 3. (a) If  $x = \sin \left( \frac{\log y}{a} \right)$  then evaluate the value

$$(1-x^2)y_{n+1} - (2n+1)x y_{n+1} - (n^2+a^2)y_n = 0$$

with usual symbols.

Ans. We have,  $x = \sin \left( \frac{\log y}{a} \right)$

$$\Rightarrow \frac{\log y}{a} = a \sin^{-1} x$$

$$\Rightarrow y = e^{a \sin^{-1} x} \quad \dots(1)$$

$$\begin{bmatrix} \because \log a = x \\ a = e^x \end{bmatrix}$$

Differentiation (i) w. r. t. x,

$$y_1 = e^{a \sin^{-1} x} \cdot \frac{d}{dx} (a \sin^{-1} x)$$

$$\Rightarrow y_1 = e^{a \sin^{-1} x} a \frac{1}{\sqrt{1-x^2}}$$

$$\Rightarrow \sqrt{1-x^2} \cdot y_1 = a \cdot e^{a \sin^{-1} x}$$

$$\Rightarrow \sqrt{1-x^2} y_1 = ay \quad [\because e^{a \sin^{-1} x} = y]$$

Squaring both sides, we get,  $(1-x^2)y_1^2 = a^2 y^2$

$$\begin{aligned} \Rightarrow \frac{d}{dx} [(1-x^2)y_1^2] &= \frac{d}{dx} [a^2 y^2] \\ \Rightarrow (1-x^2) \frac{d}{dx} (y_1^2) + (-2x) y_1^2 &= a^2 \left( 2y \frac{dy}{dx} \right) \\ (1-x^2) 2y_1 \frac{dy_1}{dx} - 2x y_1^2 &= 2a^2 y y_1 \quad \left[ \because \frac{dy}{dx} = y_1 \right] \\ \Rightarrow 2(1-x^2)y_1 y_2 - 2x y_1^2 &= 2a^2 y y_1 \quad \left[ \because \frac{dy_1}{dx} = y_2 \right] \\ \Rightarrow 2y_1 [(1-x^2)y_2 - x(y_1)] &= 2y_1 [a^2 y] \\ \Rightarrow (1-x^2)y_2 - xy_1 - a^2 y &= 0 \end{aligned} \quad \dots(2)$$

Differentiating (2)  $n$  times by Leibnitz's theorem, we get,

$$\begin{aligned} &[(1-x^2)y_{n+2} + {}^n c_1 (-2x)(y_{n+1}) + {}^n c_2 (-2)y_n] - \\ &\quad [xy_{n+1} + {}^n c_1 (1)y_n] - a^2 y_n = 0 \\ \Rightarrow &(1-x^2)y_{n+2} - 2nx y_{n+1} - \frac{n(n-1)}{2} \cdot 2y_n - \\ &\quad [xy_{n+1} + ny_n] - a^2 y_n = 0 \quad \left[ \because {}^n c_1 = n \text{ and } {}^n c_2 = \frac{n(n-1)}{2} \right] \\ \Rightarrow &(1-x^2)y_{n+2} - 2nx y_{n+1} - n(n-1)y_n - x \\ &\quad y_{n+1} - xy_n - a^2 y_n = 0 \\ \Rightarrow &(1-x^2)y_{n+2} - (2n+1)xy_{n+1} - [n(n-1)+n \\ &\quad + a^2]y_n = 0 \\ \Rightarrow &(1-x^2)y_{n+2} - (2n+1)xy_{n+1} - (n^2+a^2)y_n = 0. \end{aligned}$$

Hence Proved

Q.3. (b) If  $u = \cos^{-1} \left( \frac{x+y}{\sqrt{x+y}} \right)$ , show that

$$x \frac{du}{dx} + y \frac{du}{dy} + \frac{1}{2} \cot u = 0$$

Ans. We have  $u = \cos^{-1} \left( \frac{x+y}{\sqrt{x+y}} \right)$

$$\Rightarrow \cos u = \frac{x+y}{\sqrt{x+y}}$$

$$\text{Let } v(x, y) = \frac{x+y}{\sqrt{x+y}}$$

$$= x_1 \left[ 1 + \frac{\left( 1 + \frac{y}{x} \right)}{\sqrt{x} \left( 1 + \frac{\sqrt{y}}{\sqrt{x}} \right)} \right] \\ = x^{\frac{1}{2}} f \left( \frac{y}{x} \right)$$

Thus,  $v(x, y)$  is a homogeneous function of degree  $+\frac{1}{2}$

$$\begin{aligned} \therefore \text{By Euler's theorem, } x \frac{\partial v}{\partial x} + y \frac{\partial v}{\partial y} &= nV \\ \Rightarrow x \frac{\partial v}{\partial x} + y \frac{\partial v}{\partial y} &= +\frac{1}{2} V \quad \left[ \because n = +\frac{1}{2} \text{ here} \right] \\ \Rightarrow x \frac{\partial}{\partial x} (\cos u) + y \frac{\partial}{\partial y} (\cos u) &= +\frac{1}{2} \cos u \\ &\quad \left[ \because \frac{x+y}{\sqrt{x+y}} = V = \cos u \right] \\ \Rightarrow x \frac{\partial}{\partial u} (\cos u) \cdot \frac{\partial u}{\partial x} + y \frac{\partial}{\partial u} (\cos u) \cdot \frac{\partial u}{\partial y} &= +\frac{1}{2} \cos u \\ \Rightarrow x (-\sin u) \frac{\partial u}{\partial x} + y (-\sin u) \frac{\partial u}{\partial y} &= +\frac{1}{2} \cos u \end{aligned}$$

$$\Rightarrow -\sin u \left[ x \frac{\partial u}{\partial x} + y \frac{\partial u}{\partial y} \right] = +\frac{1}{2} \cos u$$

$$\Rightarrow x \frac{\partial u}{\partial x} + y \frac{\partial u}{\partial y} = -\frac{1}{2} \frac{\cos u}{\sin u}$$

$$\begin{aligned} \Rightarrow x \frac{\partial u}{\partial x} + y \frac{\partial u}{\partial y} &= -\frac{1}{2} \cot u \quad \left[ \because \frac{\cos \theta}{\sin \theta} = \cot \theta \right] \\ \Rightarrow x \frac{\partial u}{\partial x} + y \frac{\partial u}{\partial y} + \frac{1}{2} \cot u &= 0 \quad \text{Hence Proved} \end{aligned}$$

Q.3. (c) Verify Euler's theorem for

$$z = \frac{x^{1/3} + y^{1/3}}{x^{1/2} + y^{1/2}}$$

$$\text{Ans. We have, } z = \frac{x^{\frac{1}{2}} + y^{\frac{1}{3}}}{x^{\frac{1}{2}} + y^{\frac{1}{2}}}$$

To verify Euler's theorem for  $z$ , we shall first find degree of  $z$ .

$$\begin{aligned} \therefore z &= \frac{x^{\frac{1}{2}} + y^{\frac{1}{3}}}{x^{\frac{1}{2}} + y^{\frac{1}{2}}} \\ &= \frac{x^{\frac{1}{3}} \left( 1 + \frac{y^{\frac{1}{3}}}{x^{\frac{1}{3}}} \right)}{x^{\frac{1}{2}} \left( 1 + \frac{y^{\frac{1}{2}}}{x^{\frac{1}{2}}} \right)} \\ &= x^{\frac{1}{3} - \frac{1}{2}} \left[ \frac{1 + \left( \frac{y}{x} \right)^{\frac{1}{3}}}{1 + \left( \frac{y}{x} \right)^{\frac{1}{2}}} \right] \\ &= x^{\frac{2-3}{6}} f\left(\frac{y}{x}\right) \left[ \text{where } \frac{1 + \left( \frac{y}{x} \right)^{\frac{1}{3}}}{1 + \left( \frac{y}{x} \right)^{\frac{1}{2}}} = f\left(\frac{y}{x}\right) \right] \\ &= x^{-\frac{1}{6}} f\left(\frac{y}{x}\right) \end{aligned}$$

$\Rightarrow z$  is a homogeneous function of degree  $-\frac{1}{6}$ .

$\therefore$  To verify Euler's theorem for  $z$ , we shall show,

$$x \frac{\partial z}{\partial x} + y \frac{\partial z}{\partial y} = -\frac{1}{6}.$$

$$\left. \begin{aligned} &\because \text{Euler's theorem states} \\ &x \frac{\partial z}{\partial x} + y \frac{\partial z}{\partial y} = nz, \text{ when } n \text{ is degree} \\ &\text{of homogeneous function } z \end{aligned} \right]$$

$$\begin{aligned} \text{Now, } \frac{\partial z}{\partial x} &= \frac{\partial}{\partial x} \left[ \frac{\frac{1}{3} \left( x^{\frac{1}{2}} + y^{\frac{1}{2}} \right)}{x^{\frac{1}{2}} + y^{\frac{1}{2}}} \right] \\ &= \frac{\left( \frac{1}{x^{\frac{1}{2}}} + y^{\frac{1}{2}} \right) - \left( \frac{1}{x^{\frac{1}{2}}} + y^{\frac{1}{2}} \right) \left( \frac{1}{2} x^{-\frac{1}{2}} \right)}{\left( x^{\frac{1}{2}} + y^{\frac{1}{2}} \right)^2} \\ &= \frac{\frac{1}{3} \left( x^{\frac{1}{2}} + y^{\frac{1}{2}} \right) x^{\frac{1}{3}} - \frac{1}{2} \left( x^{\frac{1}{2}} + y^{\frac{1}{2}} \right) x^{\frac{1}{2}}}{\left( x^{\frac{1}{2}} + y^{\frac{1}{2}} \right)^2} \quad \dots(1) \end{aligned}$$

Similarly,

$$y \frac{\partial z}{\partial y} = \frac{\frac{1}{3} \left( x^{\frac{1}{2}} + y^{\frac{1}{2}} \right) y^{\frac{1}{3}} - \frac{1}{2} \left( x^{\frac{1}{2}} + y^{\frac{1}{2}} \right) y^{\frac{1}{2}}}{\left( x^{\frac{1}{2}} + y^{\frac{1}{2}} \right)^2} \quad \dots(2)$$

(Replacing  $x$  by  $y$  in (1))

Adding (1) and (2),

$$\begin{aligned} &= x \frac{\partial z}{\partial x} + y \frac{\partial z}{\partial y} \\ &= \frac{1}{\left( x^{\frac{1}{2}} + y^{\frac{1}{2}} \right)^2} \left[ \frac{1}{3} \left( x^{\frac{1}{2}} + y^{\frac{1}{2}} \right) x^{\frac{1}{3}} - \frac{1}{2} \left( x^{\frac{1}{2}} + y^{\frac{1}{2}} \right) \right. \\ &\quad \left. x^{\frac{1}{2}} + \frac{1}{3} \left( x^{\frac{1}{2}} + y^{\frac{1}{2}} \right) y^{\frac{1}{3}} - \frac{1}{2} \left( x^{\frac{1}{2}} + y^{\frac{1}{2}} \right) y^{\frac{1}{2}} \right] \\ &= \frac{1}{\left( x^{\frac{1}{2}} + y^{\frac{1}{2}} \right)^2} \left[ \frac{1}{3} \left( x^{\frac{1}{2}} + y^{\frac{1}{2}} \right) \left( x^{\frac{1}{3}} + y^{\frac{1}{3}} \right) - \frac{1}{2} \right. \\ &\quad \left. \left( x^{\frac{1}{2}} + y^{\frac{1}{2}} \right) \left( x^{\frac{1}{2}} + y^{\frac{1}{2}} \right) \right] \end{aligned}$$

$$\begin{aligned}
&= \frac{\left(\frac{1}{x^2} + \frac{1}{y^2}\right) \left(\frac{1}{x^3} + \frac{1}{y^3}\right) \left(\frac{1}{3} - \frac{1}{2}\right)}{\left(\frac{1}{x^2} + \frac{1}{y^2}\right)^2} \\
&= \frac{\frac{1}{x^3} + \frac{1}{y^3}}{\frac{1}{x^2} + \frac{1}{y^2}} \left(\frac{2-3}{6}\right) \\
&= -\frac{1}{6} \left(\frac{\frac{1}{x^3} + \frac{1}{y^3}}{\frac{1}{x^2} + \frac{1}{y^2}}\right) \\
&= -\frac{1}{6} z \quad \left[ \because z = \frac{\frac{1}{x^3} + \frac{1}{y^3}}{\frac{1}{x^2} + \frac{1}{y^2}} \right]
\end{aligned}$$

Thus,  $x \frac{\partial z}{\partial x} + y \frac{\partial z}{\partial y} = -\frac{1}{6} z$

Hence, Euler's theorem is verified.

**Q.4. (a)** In a plane  $\Delta ABC$ , find the maximum value of  $\cos A \cos B \cos C$

**Ans.** In  $\Delta ABC$ ,  $A + B + C = \pi$

$$\Rightarrow C = \pi - (A + B)$$

Now,

$$\begin{aligned}
\cos A \cos B \cos C &= \cos A \cos B \cos [\pi - (A + B)] \\
&= -\cos A \cos B \cos (A + B) \quad [\because \cos(\pi - \theta) = -\cos \theta]
\end{aligned}$$

Let,  $f = -\cos A \cos B \cos (A + B)$

$$\begin{aligned}
\Rightarrow \frac{\partial f}{\partial A} &= -\cos B \frac{\partial}{\partial A} [\cos A \cos (A + B)] \\
&= -\cos B [-\sin A \cos (A + B) + \cos A \sin (A + B)] \\
&= \cos B [-\sin (A + A + B)] \\
&\quad [\because \sin A \cos B + \cos A \sin B = \sin (A + B)] \\
\Rightarrow \frac{\partial f}{\partial A} &= \sin (2A + B) \cos B
\end{aligned}$$

Similarly,  $\frac{\partial f}{\partial B} = \sin (A + 2B) \cos A$

[Interchanging  $A$  and  $B$ ]

For maxima and minima

$$\frac{\partial f}{\partial A} = 0 \quad \frac{\partial f}{\partial B} = 0$$

Now,  $\frac{\partial f}{\partial A} = 0$

$$\Rightarrow \sin (2A + B) \cos B = 0$$

$$\Rightarrow \sin (2A + B) = 0$$

$\left[ \because \cos B = 0 \Rightarrow B = \frac{\pi}{2}, \text{ which is not possible} \right]$

$$\Rightarrow \sin (2A + B) = \sin \pi \quad [\because \sin \pi = 0]$$

$$\Rightarrow 2A + B = \pi$$

Similarly,

$$\frac{\partial f}{\partial B} = 0 \text{ gives, } A + 2B = \pi \quad \dots(2)$$

Equation (1) -  $2 \times$  equation (2) gives,

$$B - 4B = \pi - 2\pi$$

$$\Rightarrow -3B = -\pi$$

$$\Rightarrow B = \frac{\pi}{3}$$

Putting value of  $B$  in (1), we get,

$$2A + \frac{\pi}{3} = \pi$$

$$\Rightarrow dA = \pi - \frac{\pi}{3}$$

$$\Rightarrow 2A = \frac{2\pi}{3}$$

$$\Rightarrow A = \frac{\pi}{3}$$

Thus,  $\left(\frac{\pi}{3}, \frac{\pi}{3}\right)$  is the point where  $f$  can be

maximum or minimum.

To check the nature of  $f$  at this point, we calculate,  $r_1$ ,  $s$  and  $t$ :

$$\text{Now, } r = \frac{\partial^2 f}{\partial A^2}$$

$$\Rightarrow r = 2 \cos (2A + B) \cos B$$

$$\text{Also, } s = \frac{\partial^2 f}{\partial A \partial B}$$

$$\begin{aligned} &= \frac{\partial}{\partial A} \left[ \frac{\partial f}{\partial B} \right] = \frac{\partial}{\partial A} [\sin(A+2B) \cos A] \\ &= \cos(A+2B) \cos A - \sin(A+2B) \sin A \\ &= \cos(A+2B+A) \\ &\quad [\because \cos(A+B) = \cos A \cos B - \sin A \sin B] \end{aligned}$$

$$\Rightarrow s = \cos(2A+2B)$$

Now,

$$\begin{aligned} t &= \frac{\partial^2 f}{\partial B^2} \\ &= \frac{\partial}{\partial B} [\sin(A+2B) \cos A] \\ &= 2 \cos(A+2B) \cos A \end{aligned}$$

$$\text{At, } A = \frac{\pi}{3}, B = \frac{\pi}{3}$$

$$r = [2 \cos(2A+B) \cos B]_{\text{at } \left(\frac{\pi}{3}, \frac{\pi}{3}\right)}$$

$$\begin{aligned} &= 2 \cos\left(\frac{2\pi}{3} + \pi\right) \cos\frac{\pi}{3} \\ &= 2 \cos \pi \cos \frac{\pi}{3} = 2(-1) \cdot \frac{1}{2} \end{aligned}$$

$$\Rightarrow r = -1$$

$$s = [\cos(2A+2B) \cos B]_{\text{at } \left(\frac{\pi}{3}, \frac{\pi}{3}\right)}$$

$$= \cos\left(\frac{2\pi}{3} + \frac{2\pi}{3}\right)$$

$$= \cos\left(\pi + \frac{\pi}{3}\right)$$

$$= -\cos \frac{\pi}{3} = -\frac{1}{2}$$

$$t = [2 \cos(A+2B) \cos A]_{\text{at } \left(\frac{\pi}{3}, \frac{\pi}{3}\right)}$$

$$= 2 \cos\left(\pi + \frac{2\pi}{3}\right) \cos \frac{\pi}{3}$$

$$= 2 \cos \pi \cos \frac{\pi}{3}$$

$$= 2(-1) \left(\frac{1}{2}\right)^3 = -1$$

$$\text{Now, } rt - s^2 = s^2 = (-1)(-1) - \left(-\frac{1}{2}\right)^2$$

$$= 1 - \frac{1}{4} = \frac{3}{4} \text{ (Positive)}$$

Also,  $r = -1$  (Negative)

Thus,  $rt - s^2$  is positive and  $r$  is negative

$\therefore f$  is maximum

Maximum value of  $f$  =

$$= -\cos \frac{\pi}{3} \cos \frac{\pi}{3} \cos\left(\frac{\pi}{3} + \frac{\pi}{3}\right)$$

$$= \frac{1}{2} \times \frac{1}{2} \times \left(-\frac{1}{2}\right) = \frac{1}{8}$$

Ans.

Q. 4. (b) If  $x = e^v \sec u$ ,  $y = e^v \tan u$ , then evaluate

$$x \frac{\partial u}{\partial x} + y \frac{\partial u}{\partial y} + \frac{1}{2} \cot u = 0$$

Ans. We have,  $x = e^v \sec u$ ,  $y = e^v \tan u$

$$\frac{\partial(x, y)}{\partial(u, v)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix}$$

$$= \begin{vmatrix} e^v \sec u \tan u & e^v \sec u \\ e^v \sec^2 u & e^v \tan u \end{vmatrix}$$

$$= e^v \sec u \cdot e^v \begin{vmatrix} \tan u & \sec u \\ \sec u & \tan u \end{vmatrix}$$

[taking  $e^v \sec u$  common from  $c_1$  and  $e^v$  from  $c_2$ ]

$$= e^{2v} \sec u [\tan^2 u - \sec^2 u]$$

$$= -e^{2v} \sec u (1) \quad [\because \sec^2 \theta - \tan^2 \theta = 1]$$

$$\frac{\partial(x, y)}{\partial(u, v)} = -e^{2v} \sec u$$

Ans.

Q. 4. (c) The power 'P' required to propel a steamer of length 'l' at a speed 'u' is given by  $P = l u^3 \rho$  where  $\lambda$  is constant. If  $u$  is increased by 3% and  $l$  is decreased by 1%, find the corresponding increase in 'P'.

Ans. We are given,

$$\rho = \lambda u^3 \beta$$

... (i)

$$\therefore u \text{ is decreased by } 1\% \Rightarrow \frac{\partial l}{l} = -\frac{1}{100}$$

Taking log of both sides of (1), we get

$$\log p = \log \lambda + \log u^3 + \log l^3$$

$$[\because \log(m \rho) = \log m + \log n + \log p]$$

$$\Rightarrow \log p = \log \lambda + 3 \log u + 3 \log l$$

Taking differential, we get,

$$\Rightarrow \frac{\delta p}{p} = 0 + 3 \frac{\delta u}{u} + 3 \frac{\delta l}{l} \quad [\because \lambda \text{ is constant}] \\ [\because \text{its differential is 0}]$$

$$\Rightarrow \frac{\delta p}{p} = \frac{9}{100} - \frac{3}{100}$$

$$\Rightarrow \frac{\delta p}{p} = -\frac{6}{100}$$

Thus  $p$  is increased by 6%.

**Q.5. (a)** Show that row vectors of the matrix

$$\begin{bmatrix} 1 & 2 & -2 \\ -1 & 3 & 0 \\ 0 & -2 & 1 \end{bmatrix} \text{ are linearly independent.}$$

$$\text{Ans. Given matrix} = \begin{bmatrix} 1 & 2 & -2 \\ -1 & 3 & 0 \\ 0 & -2 & 1 \end{bmatrix}$$

To show that row vectors of given matrix are linearly independent, we take,

$$x_1 = (1, 2, -2), x_2 = (-1, 3, 0), x_3 = (0, -2, 1)$$

Consider the relation

$$\lambda_1 x_1 + \lambda_2 x_2 + \lambda_3 x_3 = 0 \\ \Rightarrow \lambda_1 (1, 2, -2) + \lambda_2 (-1, 3, 0) + \lambda_3 (0, -2) = (0, 0, 0)$$

$$\Rightarrow 1\lambda_1 - 1\lambda_2 + 1\lambda_3 = 0$$

$$2\lambda_1 + 3\lambda_2 - 2\lambda_3 = 0$$

$$-2\lambda_1 - 0\lambda_2 + 1\lambda_3 = 0$$

$$\therefore \text{co-efficient matrix } A = \begin{bmatrix} 1 & -1 & 0 \\ 2 & 3 & -2 \\ -2 & 0 & 1 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & -1 & 0 \\ 0 & 5 & -2 \\ 0 & -2 & 1 \end{bmatrix} R_2 \rightarrow R_2 - 2R_1 \\ R_3 \rightarrow R_3 + 2R_1$$

$$\sim \begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & 0 \\ 0 & -2 & 1 \end{bmatrix} R_2 \rightarrow R_2 - 2R_3$$

$$\sim \begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} R_3 \rightarrow R_3 + 2R_2$$

Which is in echelon form.

$\therefore$  Rank of  $A$  = Number of non zero row in echelon form = 3

$\therefore$  Rank of  $A$  = 3 = Number of unknown

$\Rightarrow$  System has only trixial sdn.

$\Rightarrow l_1, l_2, l_3$  can have only zero value.

$\therefore X_1, X_2$  and  $X_3$  are linearly independent. Thus, row vectors of given matrix are linearly independent.

**Q.5. (b)** Find the rank of the following matrix using elementary transformations

$$\begin{bmatrix} 1 & -3 & 1 & 2 \\ 0 & 1 & 2 & 3 \\ 3 & 4 & 1 & -2 \end{bmatrix}$$

$$\text{Ans. Given matrix } A = \begin{bmatrix} 1 & -3 & 1 & 2 \\ 0 & 1 & 2 & 3 \\ 3 & 4 & 1 & -2 \end{bmatrix}$$

To find the rank of  $A$ , we shall convert it into echelon form.

$$\text{Now, } A = \begin{bmatrix} 1 & -3 & 1 & 2 \\ 0 & 1 & 2 & 3 \\ 3 & 4 & 1 & -2 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & -3 & 1 & 2 \\ 0 & 1 & 2 & 3 \\ 0 & 13 & -2 & -8 \end{bmatrix} R_3 \rightarrow R_3 - 3R_1$$

$$\sim \begin{bmatrix} 1 & -3 & 1 & 2 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & -28 & -47 \end{bmatrix} R_3 \rightarrow R_3 - 13R_2$$

Which is in echelon form

$\therefore$  Rank of  $A$  = number of non zero rows in its echelon form. = 3  
Ans.

**Q.5. (c) Express the matrix**

$$A \begin{bmatrix} i & 2-3i & 4+5i \\ 6+i & 0 & 4-5i \\ -i & 2-i & 2+i \end{bmatrix} \text{ as a sum of Hermitian}$$

and Skew Hermitian matrix.

$$\text{Ans. Given matrix } A = \begin{bmatrix} i & 2-3i & 4+5i \\ 6+i & 0 & 4-5i \\ -i & 2-i & 2+i \end{bmatrix}$$

We know that for any square matrix  $A$ ,

$$A = \frac{1}{2}(A + A\theta) + \frac{1}{2}(A - A\theta) \quad \dots(1)$$

where,  $A\theta = (\bar{A})$

Here,  $(A - A\theta)$  is skew Hermitian matrix.

We shall calculate  $AQ$  now.

$$\therefore A = \begin{bmatrix} i & 2-3i & 4+5i \\ 6+i & 0 & 4-5i \\ -i & 2-i & 2+i \end{bmatrix} \quad \dots(2)$$

$$\Rightarrow \bar{A} = \begin{bmatrix} -i & 2+3i & 4-5i \\ 6-i & 0 & 4+5i \\ i & 2+i & 2-i \end{bmatrix} \quad [\text{Replacing } i \text{ by } -i]$$

$$\Rightarrow (\bar{A})' = \begin{bmatrix} -i & 6-i & i \\ 2+3i & 0 & 2+i \\ 4+5i & 4+5i & 2-i \end{bmatrix} \quad [\text{Interchanging rows and columns}]$$

$$\Rightarrow AQ = \begin{bmatrix} -i & 6-i & i \\ 2+3i & 0 & 2+i \\ 4-5i & 4+5i & 2-i \end{bmatrix} (-3)$$

$$\text{Now, } A + AQ = \begin{bmatrix} i & 2-3i & 4+5i \\ 6+i & 0 & 4-5i \\ i & 2-i & 2+i \end{bmatrix}$$

$$+ \begin{bmatrix} -i & 6-i & i \\ 2+3i & 0 & 2+i \\ 4-5i & 4+5i & 2-i \end{bmatrix}$$

$$\Rightarrow A + AQ = \begin{bmatrix} 0 & 8-4i & 4+6i \\ 8+4i & 0 & 6-4i \\ 4-6i & 6+4i & 4 \end{bmatrix}$$

$$\Rightarrow \frac{1}{2}(A + AQ) = \begin{bmatrix} 0 & 4-2i & 2+3i \\ 4+2i & 0 & 3-2i \\ 2-3i & 3+2i & 2 \end{bmatrix} \quad [\text{Dividing each element by 2}]$$

Again,

$$A - AQ = \begin{bmatrix} i & 2-3i & 4+5i \\ 6+i & 0 & 4-5i \\ i & 2-i & 2+i \end{bmatrix}$$

$$- \begin{bmatrix} i & 6i & i \\ 2+3i & 0 & 2+i \\ 4-5i & 4+5i & 2-i \end{bmatrix}$$

$$\Rightarrow (A - AQ) = - \begin{bmatrix} 2i & -4-2i & 4+4i \\ 4-2i & 0 & 2-6i \\ -4+4i & -2-6i & 2i \end{bmatrix}$$

$$\Rightarrow \frac{1}{2}(A - AQ) = \begin{bmatrix} i & -2-i & 2+2i \\ 2-i & 0 & 1-3i \\ -2+2i & -1-3i & i \end{bmatrix}$$

[Dividing each element by 2]

$$\text{Putting, } \frac{1}{2}(A + AQ) \text{ and } \frac{1}{2}(A - AQ) \text{ in (1),}$$

we get

$$A = \begin{bmatrix} 0 & 4-2i & 2+3i \\ 4+2i & 0 & 3-2i \\ 2-3i & 3+2i & 2 \end{bmatrix}$$

$$+ \begin{bmatrix} i & -2-i & 2+2i \\ 2-i & 0 & 1-3i \\ -2+2i & -1-3i & i \end{bmatrix}$$

Which is desired representation.

**Q.6. (a) Interpret the physical meaning of curl  $\vec{F}$  and div  $\vec{F}$**

**Ans. Physical meaning of curl  $\vec{F}$ :** Suppose a rigid body is rotating about a fixed axis through the origin

with linear velocity  $\vec{F}$ . Curl of  $\vec{F}$  gives 2 times the angular velocity of the body. Thus, curl is a measure of rotation.

**Physical meaning of div  $\vec{F}$ :** Consider the steady motion of a fluid having velocity  $\vec{F}$ . Rate of change of the volume of the fluid per unit time per unit volume is given by div  $\vec{F}$ .

**Q.6. (b) Verify the divergence theorem for the function  $\vec{F} = 4xz \hat{i} - y^2 \hat{j} + yz \hat{k}$ ; taken over the cube bounded by planes  $x = 0, x = 1; y = 0, y = 1; z = 0, z = 1$ .**

**Ans.** Given function,  $\vec{F} = 4xz \hat{i} - y^2 \hat{j} + yz \hat{k}$

To verify divergence theorem, we shall show that

$$\iiint_v \nabla \cdot \vec{F} dv = \iint_s \vec{F} \cdot \hat{n} ds, \text{ where } s \text{ is the given surface}$$

and  $V$  is the volume bounded by  $S$ .

Now,

$$\nabla \vec{F} = \frac{\partial F_1}{\partial x} \hat{i} + \frac{\partial F_2}{\partial y} \hat{j} + \frac{\partial F_3}{\partial z} \hat{k}$$

$$[\text{If } \vec{F} = F_1 \hat{i} + F_2 \hat{j} + F_3 \hat{k}]$$

$$\begin{aligned} \Rightarrow \nabla \vec{F} &= \frac{\partial}{\partial x}(4xz) + \frac{\partial}{\partial y}(-y^2) + \frac{\partial}{\partial z}(yz) \\ &= 4z - 2y + y \\ &= 4z - y \end{aligned}$$

$$\Rightarrow \iiint_v \nabla \cdot \vec{F} dv = \iiint_v (4z - y) dx dy dz$$

Now,  $V$  is the volume bounded by plane  $x = 0, x = 1; y = 0, y = 1$  and  $z = 0, z = 1$

$\therefore$  Limits of  $x$  are 0 to 1

Limits of  $y$  are 0 to 1

Limits of  $z$  are 0 to 1

$$\Rightarrow \iiint_v \nabla \cdot \vec{F} dv = \int_{x=0}^1 \int_{y=0}^1 \int_{z=0}^1 (4z - y) dz dy dx$$

$$= \int_{x=0}^1 \int_{y=0}^1 \left[ \frac{4z^2}{2} - yz \right]_{z=0}^1 . dy dx$$

$$= \int_{x=0}^1 \int_{y=0}^1 [2 - y] dy dx$$

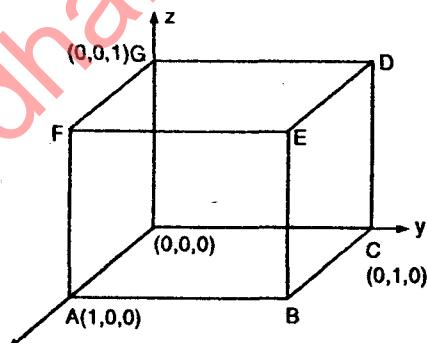
$$= \int_{x=0}^1 \left[ 2y - \frac{y^2}{2} \right]_{y=0}^1 dx$$

$$= \int_{x=0}^1 \left( 2 - \frac{1}{2} \right) dx$$

$$= \frac{3}{2} \int_0^1 dx = \frac{3}{2}$$

Thus,  $\boxed{\iiint_v \nabla \cdot \vec{F} dv = \frac{3}{2}}$  ... (1)

The surface of given cube is shown in the figure



To calculate  $\iint_s \vec{F} \cdot \hat{n} ds$ , we shall calculate surface integral for each face of the cube and then their sum.

For this, we make the following table.

Surface	Equation	$ds$	$\hat{n}$	$\vec{F} \cdot \hat{n}$
OABC	$z = 0$	$dx dy$	$-\hat{k}$	$-yz = 0$
BCDE	$y = 1$	$dx dz$	$\hat{j}$	$-y^2 = 0$
DEFG	$z = 1$	$dx dy$	$\hat{k}$	$yz = y$
OCDG	$x = 0$	$dy dz$	$-\hat{i}$	$-4xz = 0$
AOGF	$y = 0$	$dx dz$	$-\hat{j}$	$y^2 = 0$
ABEF	$x = 1$	$dy dz$	$\hat{i}$	$4xz = 4z$

$$+ yz \hat{i}) \cdot \hat{n}$$

$$OABC \quad z = 0 \quad dx dy \quad -\hat{k} \quad -yz = 0$$

$$BCDE \quad y = 1 \quad dx dz \quad \hat{j} \quad -y^2 = 0$$

$$DEFG \quad z = 1 \quad dx dy \quad \hat{k} \quad yz = y$$

$$OCDG \quad x = 0 \quad dy dz \quad -\hat{i} \quad -4xz = 0$$

$$AOGF \quad y = 0 \quad dx dz \quad -\hat{j} \quad y^2 = 0$$

$$ABEF \quad x = 1 \quad dy dz \quad \hat{i} \quad 4xz = 4z$$

Now,  $\iint_{OABC} \vec{F} \cdot \hat{n} ds = \iint_{OABC} 0 \cdot dx dy = 0$

$$\iint_{BCDE} \vec{F} \cdot \hat{n} ds = \iint_{BCDE} (-1) dx dz$$

$$= - \int_{x=0}^1 \int_{z=0}^1 dx dz$$

$$= - \int_{x=0}^1 [z]_0^1 dx$$

$$= - \int_{x=0}^1 dx = 1$$

$$\iint_{DEFG} \vec{F} \cdot \hat{n} ds = \iint_{DEFG} y dxdy$$

$$= \int_{x=0}^1 \int_{y=0}^1 y dy dx$$

$$= \int_{x=0}^1 \left[ \frac{y^2}{2} \right]_{y=0}^1 dx$$

$$= \int_{x=0}^1 \frac{1}{2} dx$$

$$= \frac{1}{2} [x]_0^1 = \frac{1}{2}$$

$$= \iint_{OCDG} \vec{F} \cdot \hat{n} ds = \iint_{OCDG} 0 dy dz = 0$$

$$= \iint_{AOGF} \vec{F} \cdot \hat{n} ds = \iint_{AOGF} 0 dx dz = 0$$

$$= \iint_{ABEF} \vec{F} \cdot \hat{n} ds = \iint_{ABEF} 4z dy dz$$

$$= \int_{y=0}^1 \int_{z=0}^1 4z dz dy$$

$$= 4 \int_{y=0}^1 \left[ \frac{z^2}{2} \right]_0^1 dy$$

$$= \frac{4}{2} \int_{y=0}^1 dy = 2$$

Adding all above integrals,

$$\iint_{OABC} \vec{F} \cdot \hat{n} ds + \iint_{BCDE} \vec{F} \cdot \hat{n} ds + \iint_{DEFG} \vec{F} \cdot \hat{n} ds$$

$$+ \iint_{OCDG} \vec{F} \cdot \hat{n} ds + \iint_{AOGF} \vec{F} \cdot \hat{n} ds + \iint_{ABEF} \vec{F} \cdot \hat{n} ds$$

$$= 0 - 1 + \frac{1}{2} + 0 + 0 + 2$$

$$\Rightarrow \iint_S \vec{F} \cdot \hat{n} ds = \frac{3}{2}$$

$$\text{Thus, } \iiint_V \nabla \cdot \vec{F} dv = \iint_S \vec{F} \cdot \hat{n} ds$$

Hence, divergence theorem is verified.

**Q.6. (c)** If a vector field is given by

$\vec{F} = (x^2 - y^2 + x) \hat{i} - (2xy + y) \hat{j}$ . Is this field irrotational? If so, find its scalar potential.

**Ans.** Given vector field

$$\vec{F} = (x^2 - y^2 + x) \hat{i} - (2xy + y) \hat{j}$$

To check that  $\vec{F}$  is irrotational, we shall find  $\nabla \times \vec{F}$ .

Now,

$$\nabla \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_1 & F_2 & F_3 \end{vmatrix}$$

$$\Rightarrow \nabla \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x^2 + y^2 + x & -2xy - y & 0 \end{vmatrix}$$

$$= \hat{i} [0 - 0] - \hat{j} [0 - 0] + \hat{k} [-2y + 2y]$$

Thus,  $\nabla \times \vec{F} = 0$

$\Rightarrow \vec{F}$  is irrotational. Let  $\phi$  be the scalar potential

$$\Rightarrow \vec{F} = \nabla \phi$$

$$\Rightarrow \vec{F} \cdot d\vec{r}$$

$$\Rightarrow d\phi = \vec{F} \cdot d\vec{r} \quad [\because \nabla \phi \cdot d\vec{r} = d\phi]$$

$$\Rightarrow d\phi = [(x^2 - y^2 + x) \hat{i} - (2xy + y) \hat{j}] \cdot d\vec{r}$$

$$\Rightarrow d\phi = (x^2 - y^2 + x) dx - (2xy + y) dy$$

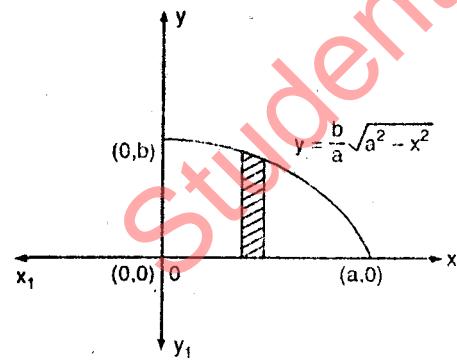
$$\begin{aligned}
 & \left[ \hat{r} = x\hat{i} + y\hat{j} + z\hat{k} \right] \\
 & \Rightarrow d\hat{r} = dx\hat{i} + dy\hat{j} + dz\hat{k} \\
 \Rightarrow d\phi &= x^2 dx - y^2 dy + xdx - 2xydy - ydy \\
 \Rightarrow d\phi &= x^2 dx + xdx - ydy - (y^2 s + 2xydy) \\
 \Rightarrow d\phi &= d\left(\frac{x^3}{3}\right) + d\left(\frac{x^2}{2}\right) - d\left(\frac{y^2}{2}\right) - d(xy^2) \\
 \text{Integrating} \\
 \boxed{\phi = \frac{x^3}{3} + \frac{x^2}{2} - \frac{y^2}{2} - xy^2 + c} & \quad \text{Ans.}
 \end{aligned}$$

**Q.7. (a)** Evaluate  $\iint_R \left(1 - \frac{x^2}{a^2} + \frac{y^2}{b^2}\right) dx dy$  over the first quadrant of the ellipse  $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$ .

**Ans.** Given integral  $I = \iint_R \left(1 - \frac{x^2}{a^2} + \frac{y^2}{b^2}\right) dx dy$

Region of integration is positive quadrant of the ellipse

$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$ , which is shown in figure.



Limits of  $x$  are from 0 to  $a$

Limits of  $y$  are from 0 to  $\frac{b}{a} \sqrt{a^2 - x^2}$

$\Rightarrow$  Given integral,

$$I = \int_{x=0}^a \int_{y=0}^{\frac{b}{a} \sqrt{a^2 - x^2}} \left(1 - \frac{x^2}{a^2} + \frac{y^2}{b^2}\right) dx dy$$

$$\begin{aligned}
 &= \int_{x=0}^a \left[ \left(1 - \frac{x^2}{a^2}\right)y + \frac{y^3}{3b^2} \right]_{y=0}^{\frac{b}{a} \sqrt{a^2 - x^2}} \\
 &= \int_{x=0}^a \left[ \left(1 - \frac{x^2}{a^2}\right) \frac{b}{a} \sqrt{a^2 - x^2} \right. \\
 &\quad \left. + \frac{1}{3b^2} \left(\frac{b}{a} \sqrt{a^2 - x^2}\right)^3 \right] dx
 \end{aligned}$$

$$\begin{aligned}
 &= \int_{x=0}^a \left[ \frac{1}{a^2} (a^2 - x^2) \frac{b}{a} \sqrt{a^2 - x^2} \right. \\
 &\quad \left. + \frac{b^3}{3a^3 b^2} \left(a^2 - x^2, \frac{3}{2}\right) \right] dx \\
 &= \int_{x=0}^a \left[ \frac{b}{a^3} (a^2 - x^2)^{\frac{3}{2}} + \frac{b}{3a^3} \left(a^2 - x^2, \frac{3}{2}\right) \right] dx
 \end{aligned}$$

$$= \int_{x=0}^a \frac{b}{3a^3} (a^2 - x^2)^{\frac{3}{2}} (3+1) dx$$

$$\Rightarrow I = \frac{4b}{3a^3} \int_0^a (a^2 - x^2)^{3/2} dx$$

$$\text{Put, } x = a \sin \theta$$

$$\Rightarrow dx = a \cos \theta d\theta$$

$$\text{at } x = 0, \sin \theta = 0 \Rightarrow \theta = 0$$

$$\text{at } x = a, \sin \theta = 1 \Rightarrow \theta = \frac{\pi}{2}$$

$$\Rightarrow I = \frac{4b}{3a^3} \int_0^{\frac{\pi}{2}} (a^2 - a^2 \sin^2 \theta)^{3/2} a \cos \theta d\theta$$

$$= \frac{4b}{3a^2} \int_0^{\frac{\pi}{2}} [a^2 (1 - \sin^2 \theta)]^{3/2} \cos \theta d\theta$$

$$= \frac{4b}{3a^2} \int_0^{\frac{\pi}{2}} a^3 \cos^3 \theta \cos \theta d\theta$$

$$= \frac{4}{3} ab \int_0^{\frac{\pi}{2}} \sin \theta \cos 4\theta d\theta$$

$$= \frac{4}{3} ab \frac{\frac{2}{2}}{2 \left| \begin{array}{|c|c|} \hline 0+1 & 4+1 \\ \hline 0+4+2 & \\ \hline \end{array} \right|}$$

$$\left[ \begin{array}{l} \therefore \int_0^{\frac{\pi}{2}} \sin p\theta \cos^2 \theta d\theta \\ = \frac{2}{2 \left| \begin{array}{|c|c|} \hline p+1 & q+1 \\ \hline p+q+2 & \\ \hline \end{array} \right|} \end{array} \right]$$

$$= \frac{2}{3} ab \frac{\frac{1}{2} \left| \begin{array}{|c|c|} \hline 1 & 5 \\ \hline 2 & 2 \\ \hline \end{array} \right|}{\sqrt{3}}$$

$$= \frac{2}{3} ab \frac{\sqrt{\pi} \frac{3}{2} \cdot \frac{1}{2} \sqrt{\pi}}{2!} \quad \left[ \because \left| \begin{array}{|c|c|} \hline 1 & \\ \hline 2 & \\ \hline \end{array} \right| = \sqrt{\pi} \right]$$

$$= \frac{\pi ab}{4}$$

Ans.

**Q.7. (b) Find the mass of the region bounded by**

$$\text{ellipsoid } \frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1; \text{ if the density varies}$$

as the square of the distance from the centre.

$$\text{Ans. Given ellipsoid is } \frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$$

Let  $f$  be the density at a point  $(x, y, z)$

$\therefore$  Density varies as the square of the distance from centre.

$\therefore$  We shall find distance of  $(x, y, z)$  from centre  $(0, 0, 0)$ . By distance formula, distance  $d$  between points  $(x_1, y_1, z_1)$  and  $(x_2, y_2, z_2)$  is

$$d = \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2 + (z_1 - z_2)^2}$$

$$\Rightarrow d = \sqrt{(x - 0)^2 + (y - 0)^2 + (z - 0)^2}$$

$$\Rightarrow d^2 = x^2 + y^2 + z^2$$

$\therefore f = kd^2$  (where  $k$  is constant)

$$\Rightarrow f = k(x^2 + y^2 + z^2)$$

Now, mass =  $\iiint_V \rho dx dy dz$ , where  $r$  is the volume of given ellipsoidal.

$$= k \iiint_V (x^2 + y^2 + z^2) dx dy dz$$

Putting,  $x = ar \sin \theta \cos \phi$

$$y = br \sin \theta \sin \phi$$

$$z = cr \cos \theta$$

[changing to ellipsoidal polar coordinates]

$$dx dy dz = abc r^2 \sin \theta dr d\theta d\phi$$

Limits of  $r$  are 0 to 1

Limits of  $\theta$  are 0 to  $\pi$

Limits of  $\phi$  are 0 to  $2\pi$

$\Rightarrow$  Mass

$$= k \int_{\theta=0}^{\pi} \int_{\phi=0}^{2\pi} \int_{r=0}^1 [a^2 r^2 \sin^2 \theta \cos^2 \phi + b^2 r^2 \sin^2 \theta \sin^2 \phi + c^2 r^2 \cos^2 \theta] abc r^2 \sin \theta dr d\theta d\phi$$

$$= kab \int_{\theta=0}^{\pi} \int_{\phi=0}^{2\pi} \int_{r=0}^1 [a^2 \sin^2 \theta \cos^2 \phi + b^2 \sin^2 \theta \sin^2 \phi + c^2 \cos^2 \theta] \sin^2 \phi \sin \theta r^4 dr d\theta d\phi$$

$$= kab \int_{\theta=0}^{\pi} \int_{\phi=0}^{2\pi} [(a^2 \sin^2 \theta \cos^2 \phi + b^2 \sin^2 \theta \sin^2 \phi + c^2 \cos^2 \theta) \sin \theta \frac{r^5}{5}]_{r=0}^1 d\theta d\phi$$

$$= \frac{kabc}{5} \int_{\theta=0}^{\pi} \int_{\phi=0}^{2\pi} [(a^2 \sin^2 \theta \cos^2 \phi + b^2 \sin^2 \theta \sin^2 \phi + c^2 \cos^2 \theta) \sin \theta + \cos^2 \theta] \sin \theta d\theta d\phi$$

$$= \frac{kabc}{5} \int_{\theta=0}^{\pi} \int_{\phi=0}^{2\pi} \left[ a^2 \sin^2 \theta \left( \frac{1 + \cos 2\phi}{2} \right) + b^2 \sin^2 \theta \left( \frac{1 - \cos 2\phi}{2} \right) + c^2 \cos^2 \theta \right] \sin \theta d\phi d\theta$$

$$= \frac{kabc}{5} \int_{\theta=0}^{\pi} \left[ \frac{a^2 \sin^2 \theta}{2} \left( \theta + \frac{\sin 2\phi}{2} \right) + \frac{b^2 \sin^2 \theta}{2} \left( \phi - \frac{\sin 2\phi}{2} \right) + \frac{c^2 \cos^2 \theta}{2} \right] \sin \theta d\theta$$

$$\left[ \phi - \frac{\sin 2\phi}{2} \right]_{\phi=0}^{2\pi} + c^2 \cos \theta \cdot \phi \sin \theta d\theta$$

$$\begin{aligned}
&= \frac{kabc}{5} \int_{\theta=0}^{\pi} \left[ \frac{a^2 \sin^2 \phi}{2} (2\pi) + \frac{b^2 \sin^2 \theta}{2} (2\pi) \right. \\
&\quad \left. (2\pi) + c^2 \cos^2 \theta (2\pi) \right] \sin \theta d\theta \\
&= \pi \frac{kabc}{5} \int_{\theta=0}^{\pi} [(a^2 + b^2) \sin^2 \theta + 2c^2 \cos^2 \theta] \\
&\quad \sin \theta \sin \theta \\
&= \pi \frac{kabc}{5} \int_{\theta=0}^{\pi} [(x^2 + b^2) - (a^2 + b^2) \cos^2 \theta \\
&\quad + 2c^2 \cos^2 \theta] \sin \theta d\theta \\
&= \pi \frac{kabc}{5} \int_{\theta=0}^{\pi} [(a^2 + b^2) \sin \theta d\theta + \\
&\quad \pi \frac{kabc}{5} \int_{\theta=0}^{\pi} (2c^2 - a^2 - b^2) \cos^2 \theta \sin \theta d\theta \\
&= \pi \frac{kabc}{5} (a^2 + b^2) (-\cos \theta)_0^{\pi} + \\
&= \pi \frac{kabc}{5} (2c^2 - a^2 - b^2) I,
\end{aligned}$$

where  $I = \int_0^{\pi} \cos^2 \theta s, h \theta d\theta$

$$= \frac{\pi kabc}{5} (a^2 + b^2) (2) + \frac{\pi kabc}{5} (2c^2 - a^2 - b^2) I$$

Now, we shall calculate I

$$\begin{aligned}
\therefore I &= \int_0^{\pi} \cos^2 \theta \sin d\theta \\
&= - \int_{-1}^1 t^2 dt \\
&= - \left[ \frac{t^3}{3} \right]_{-1}^1 \\
&= - \left[ \frac{-1}{3} - \frac{1}{3} \right] = \frac{2}{3}
\end{aligned}$$

$$\Rightarrow \text{Mass} = 2\pi \frac{kabc}{5} (a^2 + b^2) +$$

$$\frac{\pi kabc}{5} (2c^2 - a^2 - b^2) \frac{2}{3}$$

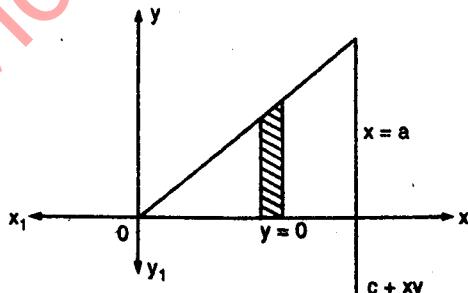
$$\begin{aligned}
&= 2\pi \frac{kabc}{5} \left[ a^2 + b^2 + \frac{2c^2 - a^2 - b^2}{3} \right] \\
&= 2\pi \frac{kabc}{15} [3a^2 + 3b^2 + 2c^2 - a^2 - b^2] \\
&= \frac{4\pi kabc}{15} (a^2 + b^2 + c^2)
\end{aligned}$$

$$\therefore \text{Required mass} = \frac{4\pi kabc}{15} (a^2 + b^2 + c^2) \text{ Ans.}$$

**Q.7. (c)** A triangular prism is formed by the planes whose equations are  $ay = bx$ ,  $y = 0$  and  $x = a$ . Find the volume of this prism between the plane  $z = 0$  and the surface  $z = c + xy$ .

$$\text{Ans. Required volume} = \iiint_V dx dy dz$$

where, V is the given region



Clearly limits of z are 0 to  $c + xy$

Limits of y are 0 to  $\frac{bx}{a}$

Limits of x are 0 to a

$$\therefore \text{Required volume} = \int_{x=0}^a \int_{y=0}^{\frac{bx}{a}} \int_{z=0}^{c+xy} dz dy dx$$

$$= \int_{x=0}^a \int_{y=0}^{\frac{bx}{a}} [z]_{z=0}^{c+xy} dy dx$$

$$\begin{aligned}
 &= \int_{x=0}^a \int_{y=0}^{\frac{bx}{a}} (c + xy) dy dx \\
 &= \int_{x=0}^a \left[ cy + \frac{xy^2}{2} \right]_{y=0}^{\frac{bx}{a}} dx \\
 &= \int_{x=0}^a \left[ \frac{cbx}{a} + \frac{x^2}{2} \left( \frac{bx}{a} \right)^2 \right] dx \\
 &= \int_{x=0}^a \left( \frac{cbx}{a} + \frac{b^2 x^3}{2a^2} \right) dx \\
 &= \left[ \frac{cb}{a} \frac{x^2}{2} + \frac{b^2}{2a^2} \frac{x^4}{4} \right]_{x=0}^a \\
 &= \frac{cb}{a} \left( \frac{a^2}{2} \right) + \frac{b^2}{8a^2} a^4 \\
 &= \frac{abc}{2} + \frac{a^2 b^2}{8} \quad \text{Ans.}
 \end{aligned}$$

StudentSuvidha.com